

**Estimates of Chinook Salmon Passage in the Kenai
River at River Mile 8.6 Using Dual-Frequency
Identification Sonar, 2013**

by

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Alaska Department of Fish and Game

Divisions of Sport Fish and Commercial Fisheries



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Weights and measures (metric)		General		Mathematics, statistics		
centimeter	cm	Alaska Administrative Code	AAC	all standard mathematical signs, symbols and abbreviations		
deciliter	dL	all commonly accepted abbreviations	e.g., Mr., Mrs., AM, PM, etc.	alternate hypothesis	H _A	
gram	g	all commonly accepted professional titles	e.g., Dr., Ph.D., R.N., etc.	base of natural logarithm	<i>e</i>	
hectare	ha			catch per unit effort	CPUE	
kilogram	kg			coefficient of variation	CV	
kilometer	km	at	@	common test statistics	(F, t, χ^2 , etc.)	
liter	L			confidence interval	CI	
meter	m			correlation coefficient (multiple)	R	
milliliter	mL	compass directions:		correlation coefficient (simple)	r	
millimeter	mm	east	E	covariance	cov	
Weights and measures (English)		north	N	degree (angular)	°	
	cubic feet per second	ft ³ /s	south	S	degrees of freedom	df
	foot	ft	west	W	expected value	<i>E</i>
	gallon	gal	copyright	©	greater than	>
	inch	in	corporate suffixes:		greater than or equal to	≥
	mile	mi	Company	Co.	harvest per unit effort	HPUE
	nautical mile	nmi	Corporation	Corp.	less than	<
	ounce	oz	Incorporated	Inc.	less than or equal to	≤
	pound	lb	Limited	Ltd.	logarithm (natural)	ln
	quart	qt	District of Columbia	D.C.	logarithm (base 10)	log
yard	yd	et alii (and others)	et al.	logarithm (specify base)	log ₂ , etc.	
Time and temperature		et cetera (and so forth)	etc.	minute (angular)	'	
		exempli gratia		not significant	NS	
	day	d	(for example)	e.g.	null hypothesis	H ₀
	degrees Celsius	°C	Federal Information Code	FIC	percent	%
	degrees Fahrenheit	°F	id est (that is)	i.e.	probability	P
	degrees kelvin	K	latitude or longitude	lat or long	probability of a type I error (rejection of the null hypothesis when true)	α
	hour	h	monetary symbols (U.S.)	\$, ¢	probability of a type II error (acceptance of the null hypothesis when false)	β
	minute	min	months (tables and figures): first three letters	Jan.,...,Dec	second (angular)	"
	second	s	registered trademark	®	standard deviation	SD
	Physics and chemistry		trademark	™	standard error	SE
all atomic symbols			United States (adjective)	U.S.	variance	
alternating current		AC	United States of America (noun)	USA	population sample	Var
ampere		A	U.S.C.	United States Code	var	
calorie		cal	U.S. state	use two-letter abbreviations (e.g., AK, WA)		
direct current		DC				
hertz		Hz				
horsepower		hp				
hydrogen ion activity (negative log of)		pH				
parts per million		ppm				
parts per thousand	ppt, ‰					
volts	V					
watts	W					

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AT RIVER MILE 8.6 USING DUAL-FREQUENCY IDENTIFICATION
SONAR, 2013**

by
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ABSTRACT

Kenai River Chinook salmon (*Oncorhynchus tshawytscha*) passage was estimated in 2013 at RM 8.6 using dual-frequency identification sonar (DIDSON). Estimates of midriver Chinook salmon passage between and at least 3 m from the transducers were 1,439 (SE 138) fish for the early run (16 May–30 June) and 15,185 (SE 566) fish for the late run (1 July–15 August). The early-run estimate is too small to explain weir counts at upriver tributaries. Methods and results from a second experimental sonar site located above tidal influence at RM 13.7 are presented in a separate report.

Key words: DIDSON, Chinook salmon, *Oncorhynchus tshawytscha*, acoustic assessment, Kenai River, riverine sonar

INTRODUCTION

Chinook salmon (*Oncorhynchus tshawytscha*) returning to the Kenai River are managed as 2 distinct runs (Burger et al. 1985): early (16 May–30 June) and late (1 July–10 August). Early-run Chinook salmon are harvested primarily by sport anglers, and late-run Chinook salmon are harvested by commercial, sport, subsistence, and personal use fisheries. These fisheries may be restricted if the projected escapement falls below goals adopted by the Alaska Board of Fisheries (BOF). These goals are defined by Alaska Administrative Codes 5 AAC 56.070 (*Kenai River and Kasilof River Early-Run King Salmon Conservation Management Plan*) and 5 AAC 21.359 (*Kenai River Late-Run King Salmon Management Plan*) and are intended to ensure sustainable Chinook salmon stocks. Escapement goals have evolved over the years as stock assessment and our understanding of stock dynamics have improved (McBride et al. 1989; Hammarstrom and Hasbrouck 1998, 1999; Bosch and Burwen 1999).

During the 2013 early run, an optimal escapement goal (OEG) range of 5,300–9,000 Chinook salmon was in effect. The late run sustainable escapement goal (SEG) range was revised from 17,800–35,700 to 15,000–30,000 Chinook salmon prior to the 2013 season to reflect the transition from split-beam sonar to DIDSON (Begich et al. 2013). Sonar estimates of inriver Chinook salmon passage provide the basis for estimating spawning escapement and implementing management plans that regulate harvest in the competing sport and commercial fisheries for this stock. Implementation of these management plans has been contentious and attracts public scrutiny. Fishery restrictions were imposed to meet escapement goals during the early run in 1990–1992, 1997, 1998, 2000, 2002, and 2010–2013; and during the late run in 1990, 1992, 1998, and 2011–2013.

PROJECT HISTORY

Mark–recapture

The first estimates of Kenai River Chinook salmon abundance were generated in 1984 for the late run using a mark–recapture project (Hammarstrom et al. 1985). This mark–recapture project produced estimates for both early- and late-run riverine abundance (Hammarstrom and Larson 1986; Conrad and Larson 1987; Conrad 1988; Carlon and Alexandersdottir 1989; Alexandersdottir and Marsh 1990). However, these mark–recapture estimates had low precision and failed to provide inseason information on Chinook salmon abundance, and they were discontinued after 1990.

Dual-beam Sonar

The Chinook salmon sonar site at river mile (RM) 8.6 was established in 1985 (Eggers et al. 1995). Unlike the sockeye salmon (*O. nerka*) sonar site at RM 19, the RM 8.6 sonar site is located downstream of all Chinook salmon spawning habitat and downstream of nearly all sport fishing for Chinook salmon. The site originally deployed dual-beam sonar technology, chosen for its ability to estimate acoustic size (target strength). Target strength (TS) is a measure of the loudness of the echo returning from a fish, corrected for position of the fish in the beam. Because of the considerable size difference between large Chinook salmon and other fish species in the Kenai River, it was postulated that target-strength measurements could be used to distinguish Chinook salmon from smaller fish (primarily sockeye salmon) and to estimate their numbers returning to the river.

Early Kenai River sonar and gillnetting studies indicated that Chinook salmon could be distinguished from sockeye salmon based on target strength and spatial separation in the river (Eggers et al. 1995). A target strength threshold was established to censor small fish. Sockeye salmon also were thought to migrate primarily near the bank, so a range or distance threshold was also imposed. From 1987 through 2011, “TS-based estimates” based on these 2 criteria were the primary basis for monitoring the number of Chinook salmon returning to the Kenai River for comparison with established escapement goals.

Split-beam Sonar

A more advanced acoustic technology, known as split-beam sonar, was used to test assumptions and design parameters of the dual-beam configuration in 1994 (Burwen et al. 1995). The split-beam system provided advantages over the dual-beam system in its ability to determine the 3-dimensional position of an acoustic target in the sonar beam. Consequently, the direction of travel for each target and the 3-dimensional spatial distribution of fish in the acoustic beam could be determined for the first time. The split-beam system also operated at a lower frequency than the dual-beam system, providing a higher (improved) signal-to-noise ratio (SNR; Simmonds and MacLennan 2005). It also interfaced with improved fish-tracking software, which reduced the interference from boat wake and improved fish-tracking capabilities (Burwen and Bosch 1996). The split-beam system was deployed side-by-side and run concurrently with the dual-beam system for much of the 1994 season (Burwen et al. 1995). The two systems detected comparable numbers of fish. The split-beam data confirmed earlier studies (Eggers et al. 1995) showing that most fish targets were strongly oriented to the river bottom. However, experiments conducted with the split-beam system could not confirm that Chinook salmon could be discriminated from sockeye salmon based on target strength. Modeling exercises performed by Eggers (1994) also questioned the feasibility of discriminating between Chinook and sockeye salmon using target strength. It was hypothesized that discrimination between the two species was primarily accomplished using range thresholds on the acoustic data that exploited the assumed spatial segregation of the species (sockeye salmon migrate near shore and Chinook salmon migrate midriver; Burwen et al. 1995; Eggers et al. 1995). In 1995, the dual-beam system was replaced with the split-beam system to take advantage of the additional information on direction of travel and spatial position of targets. TS-based estimates continued to be produced with the split-beam sonar to make comparisons across years.

Ancillary drift gillnetting and sonar studies conducted in 1995 (Burwen et al. 1998) were directed at providing definitive answers to remaining questions regarding 1) the degree to which

sockeye and Chinook salmon are spatially separated at the RM-8.6 Chinook salmon sonar site and 2) the utility of using target strength and other acoustic parameters for species separation. These studies confirmed the potential for misclassifying sockeye salmon as Chinook salmon. The drift gillnetting study found that sockeye salmon were present in the middle insonified portion of the river. In addition, most sockeye salmon in the live tethered fish experiment had mean target strengths that exceeded the target strength threshold.

Concurrent Studies to Verify and Improve Sonar Passage Estimates

Mark-recapture experiments using radiotelemetry were implemented in 1996 and 1997 to estimate the magnitude of bias introduced to the Chinook salmon passage estimates during periods of high sockeye salmon passage (Hammarstrom and Hasbrouck 1998, 1999). These studies were designed to provide an independent and accurate estimate of inriver Chinook salmon passage during the late run, when the potential to misclassify sockeye salmon using sonar was thought to be greatest. Although the precisions of radiotelemetry estimates and previous mark-recapture estimates were similar, the use of radiotelemetry avoided certain biases associated with the earlier mark-recapture studies. Sonar estimates of late-run Chinook salmon abundance were 26% greater in 1996 and 28% greater in 1997 than the corresponding telemetry estimates, assumed due to the misclassification of sockeye salmon as Chinook salmon (Hammarstrom and Hasbrouck 1998, 1999).

An investigation in 1999 (Burwen et al. 2000) attempted to identify alternative sites above tidal influence with stronger bank orientation of sockeye salmon, where range thresholds would be more effective. The investigation concentrated on a site located at RM 13.2 that was upstream of tidal influence but downstream of major spawning areas. Gillnetting data indicated that there were fewer sockeye salmon in the offshore area at the alternative site than at the current site. However, there were still relatively large numbers of sockeye salmon present in the offshore area of the alternative site during peak migration periods as well as high numbers of Chinook salmon present in the nearshore area. The alternate sonar site also had disadvantages over the current site including more boat traffic and less acoustically favorable bottom topography, both of which contributed to higher background noise and resulted in difficult fish tracking conditions.

The inriver drift gillnetting program, originally designed to collect age, sex, and length (ASL) samples (Marsh 2000), was modified in 1998 to produce standardized estimates of Chinook salmon catch per unit effort (CPUE) for use as an index of Chinook salmon passage (Reimer et al. 2002). A drift zone was established just downstream from the sonar site and crews fished relative to the tide cycles because gillnets could not be fished effectively during parts of the rising and high tide stages due to lack of river current. In addition, the schedule was intensified so that CPUE estimates could be generated daily. During subsequent years, inriver gillnet CPUE was compared with sonar passage estimates to detect periods when Chinook salmon passage estimates were potentially high because of inclusion of sockeye salmon or other species (Bosch and Burwen 2000; Miller and Burwen 2002; Miller et al. 2002-2005, 2007a-b, 2010-2012).

Analysis of the 1998–2000 standardized CPUE data suggested the gillnetting data were better suited for determining species apportionment of split-beam sonar counts than for passage estimates (Reimer et al. 2002). In 2002, the inriver gillnetting program was modified further. A 5-inch mesh gillnet was introduced, alternating with the existing 7.5-inch mesh to reduce size selectivity; nets were constructed of multi-monofilament (formerly cable-lay braided nylon); the

color of the mesh was changed to more closely match that of the river; and drifts were shortened and constrained to more closely match the portion of the channel sampled by the sonar. These changes increased netting efficiency and decreased the effect of water clarity on gillnet catches (Reimer 2004).

In 2002, the species discrimination algorithm for TS-based estimates was refined in order to reduce sensitivity of the estimates to large bursts of migrating sockeye salmon. During hourly samples when sockeye salmon were abundant, as evidenced by aggregation of migrating fish into groups, the data were censored, and Chinook salmon passage was estimated from the remaining hourly samples.

Also in 2002, two experimental methods of estimating Chinook salmon passage were initiated. The first alternative estimate, referred to as the net-apportioned estimate, used the product of Chinook salmon catch proportions from the netting program (Eskelin 2010) and sonar upstream midriver fish passage estimates (see Methods). Net-apportioned estimates have been published annually since 2002 (Miller et al. 2004-2005, 2007a-b, 2010-2012) and have proven useful for tracking short-term trends in Chinook salmon abundance.

The second alternative estimate was based on split-beam measures of echo envelope length, which is a better predictor of fish length than target strength (Burwen and Fleischman 1998; Burwen et al. 2003). Statistical methods were developed that enable robust estimates of species composition even when species overlap in size (Fleischman and Burwen 2003). Echo length standard deviation (ELSD) information from the sonar was combined with fish length data from the netting program to estimate the species composition of fish passing the sonar site. The resulting estimated proportion of Chinook salmon was then multiplied by upstream fish passage estimates from the sonar. The resulting “ELSD-based” estimates, considered to be more accurate than the official TS-based estimates, were produced for the years 2002–2006. Because echo length measurements can be corrupted when 2 or more fish swim very close to one another, resulting in higher values of ELSD, only early-run estimates were published (Miller et al. 2004-2005, 2007a-b, 2010). The corresponding late-run estimates were suspected to be too high due to high sockeye salmon densities.

In 2007, the ELSD mixture model method was modified in an attempt to reduce the bias at high fish densities. Using split-beam measurements of 3-dimensional fish location, the distance between fish was calculated and fish within 1 meter of any other fish were censored before fitting the mixture model. Essentially, fish swimming close to other fish were assumed not to be Chinook salmon. This modification reduced estimates during high densities but also had the potential to mistakenly censor Chinook salmon. ELSD-based estimates published in the 2007 report (Miller et al. 2011) supplanted the previously published early-run estimates. See Miller et al. (2014: Appendix F) for a complete record of daily ELSD-based estimates for 2002–2011. Split-beam sonar was discontinued after the 2011 season.

Dual-frequency Identification Sonar (DIDSON)

ADF&G began testing dual-frequency identification sonar (DIDSON¹) in the Kenai River in 2002 (Burwen et al. 2007). DIDSON uses a lens system that provides high-resolution images that approach the quality achieved with conventional optics (Simmonds and MacLennan 2005), with the advantage that images can be obtained in dark or turbid waters. DIDSON imagery resembles

¹ DIDSON was designed by the University of Washington Applied Physics Laboratory, originally for military applications.

somewhat pixelated video footage taken from a vantage point above the fish (see Appendices A6–A8). Fish size was immediately evident from DIDSON footage of migrating Kenai River salmon, suggesting that DIDSON had promise for improved discrimination of large Chinook salmon from smaller fish in the Kenai River. With ADF&G input, DIDSON developers designed custom software for manually measuring fish size directly from still images. Initial experiments using live tethered salmon showed that at ranges up to 12 m, precise estimates of fish length could be obtained by manually measuring fish images produced by a standard DIDSON unit (Burwen et al. 2007). Ranges to 30 m are required to adequately insonify the Kenai River at the current sonar location (RM 8.6). The development of a “long-range” DIDSON model in 2004 extended the range of high-frequency operation to approximately 30 m, and a high-resolution lens developed in 2007 improved the resolution by nearly a factor of 2. Tethered-fish experiments conducted in 2007 with the new equipment established that DIDSON-estimated fish length was closely related to true length at ranges up to 22 m (Burwen et al. 2010; Miller et al. 2011). Additional experiments conducted with multiple observers on the left bank during 2009 confirmed the 2007 results at ranges up to 32 m (Miller et al. 2012).

In the years 2007–2009, the long-range high-resolution DIDSON sonar was deployed on the left bank to sample 10 m of river cross section that was simultaneously sampled by the split-beam transducer (Miller et al. 2011–2012). Methods and equipment were developed to minimize accumulation of silt in the lens, which could result in degraded image resolution. A pilot study concluded that automated tracking and measuring of free-swimming fish were feasible and potentially advantageous under some circumstances. DIDSON exhibited multiple advantages over split-beam sonar with respect to detection, tracking, and species classification of passing fish. Frequency distributions of DIDSON length measurements, along with paired netting data, lent themselves well to mixture modeling, which enabled estimation of species composition of passing fish. Such estimates agreed well with corresponding split-beam estimates from the ELSD mixture model in 2009.

A second DIDSON system was acquired in 2010, and simultaneous coverage of both banks was achieved for 48 of 87 days (Miller et al. 2013). Comparisons of TS-based estimates with DIDSON estimates and other indices of Chinook salmon abundance showed that the assumptions underpinning TS-based estimates of Chinook salmon abundance were not valid. The DIDSON also detected large fish at short ranges that had not been sampled by the split-beam sonar or the onsite netting project.

Split-beam and DIDSON data were collected concurrently for a second full season in 2011 (Miller et al. 2014, 2015), confirming that DIDSON was better at distinguishing large from small salmon. Supplemental sampling behind the existing transducer placements in 2011 and 2012 confirmed the presence of large fish near shore. Split-beam sonar was discontinued in 2012.

Following the 2012 season, a state-space model (SSM) was fitted to sonar, netting, catch-rate, and capture–recapture data; historical abundance was reconstructed; and escapement goals (3,800–8,500 early-run; 15,000–30,000 late-run) were recommended in preparation for the 2013 season (Fleischman and McKinley 2013; McKinley and Fleischman 2013). This modeling exercise, which synthesized information from all applicable data, estimated that the proportion of Chinook salmon migrating midriver (pMR) and detected by sonar and nets at RM 8.6 was 0.65 during the early run and 0.78 during the late run. In 2013, to account for incomplete detection at RM 8.6, DIDSON estimates of inriver abundance were expanded by $(1/0.65 =) 1.55$ during the

early run and ($1/0.78 =$) 1.28 during the late run, and used inseason to assess achievement of the new escapement goals.

In this report, we present daily and seasonal DIDSON-based estimates of Chinook salmon midriver abundance for 2013. Passage estimates in this report have not been expanded for incomplete spatial coverage. Methods and results from deploying sonar at an experimental site above tidal influence at RM 13.7 are presented in a separate report (Miller et al. 2016).

OBJECTIVE

The primary objective of this project was to produce weekly and seasonal estimates of the midriver run of Chinook salmon to the Kenai River such that the seasonal estimate was within 10% of the true value 95% of the time. The precision criterion for passage estimates addresses sampling error and species classification, but not detection. Uncertainty due to incomplete spatial coverage is addressed in separate reports (Fleischman and McKinley 2013; McKinley and Fleischman 2013).

METHODS

STUDY AREA

The Kenai River drainage is approximately 2,150 square miles (Figure 1). It is glacially influenced, with discharge rates lowest during winter ($<1,800 \text{ ft}^3/\text{s}$), increasing throughout the summer, and peaking in August ($>14,000 \text{ ft}^3/\text{s}$) (Benke and Cushing 2005). The Kenai River has 10 major tributaries, many of which provide important spawning and rearing habitat for salmon. Tributaries include the Russian, Skilak, Killey, Moose, and Funny rivers.

The Kenai River drainage is located in a transitional zone between a maritime climate and a continental climate (USDA 1992). The geographic position and local topography influence both rainfall and temperature throughout the drainage. Average annual (1981–2010) precipitation for the City of Kenai, located at the mouth of the Kenai River, is 47 cm (WRCC 2016). Average summer (June, July, and August) minimum and maximum temperatures for the City of Kenai range from 8°C to 16°C (WRCC 2016).

SITE DESCRIPTION

The sonar site was located 14 km (8.6 miles) from the mouth of the Kenai River (Figure 2). This site has been used since 1985 and was selected for its acoustic characteristics and its location downstream of the sport fishery and known Chinook salmon spawning habitat.

The river bottom in this area has remained stable for the past 27 years (Bosch and Burwen 1999). The slope from both banks is gradual and uniform, which allows a large proportion of the water column to be insonified without acoustic shadowing effects. On the right bank, the bottom is composed primarily of mud, providing an acoustically absorptive surface. This absorptive property improves the signal-to-noise ratio (SNR) when the beam is aimed along the river bottom. The left-bank bottom gradient is steeper and consists of more acoustically reflective small rounded cobble and gravel.

The sonar site is located downstream of the lowest suspected Chinook salmon spawning sites, yet far enough from the mouth that most of the fish counted are probably committed to the Kenai River (Alexandersdottir and Marsh 1990). Most sport fishing activity occurs upstream of the site (Eskelin 2007).

ACOUSTIC SAMPLING

A Sound Metrics Corporation (SMC²) DIDSON system was operated from 16 May to 15 August 2013. Components of the DIDSON system are listed in Table 1. Appendices A1–A8 provide greater detail on DIDSON technology and theory.

Sonar System Configuration

A single DIDSON long-range (DIDSON-LR) equipped with an ultra-high resolution lens was deployed on each bank of the river such that each remained submerged at low tide (Figure 3). The location of each DIDSON relative to the bank varied slightly throughout the summer because the units were occasionally pulled and redeployed for maintenance purposes or after being dislodged by floating debris. A detailed discussion of DIDSON configurations and DIDSON image resolution and a brief explanation of multibeam sonar can be found in Appendices A1–A8. More detailed theory can be found in Belcher et al. (2002).

Electronics were housed in a tent located on the right (north) bank of the river (Figure 3). The DIDSON units were mounted on remote pan-and-tilt systems (right bank: Remote Ocean Systems PT-25; left bank: Sound Metrics Corporation X2) for precise aiming in the horizontal and vertical axes. The combined sonar and rotators were deployed in the river on a tripod-style mount (Figure 4, photo A). In the horizontal plane, the sonars were aimed perpendicular to the flow of the river current to maximize the probability of insonifying migrating salmon from a lateral aspect. In the vertical plane, the sonars were aimed to insonify the near-bottom region (Figure 3). Internal attitude sensors in the DIDSON provided measurements of compass heading, pitch, and roll. An AIM 2000 attitude sensor attached to the right-bank mount provided depth measurements throughout the season.

Communication cables from the right-bank DIDSON fed directly into the right-bank topside box and data collection computer. On the left bank, the DIDSON communication cable fed to a topside box staged on top of the bluff, and data were transmitted via a wireless bridge to a data collection computer on the right bank. Because silt deposition in the lens compartment can cause deterioration in both image quality and range capabilities, a custom fit fabric enclosure was used to limit silt infiltration (Figure 4, photos B and C).

River Profile Mapping and Coverage

A detailed profile of the river bottom and the area encompassed by the sonar beams was produced prior to acoustic sampling. Depth readings collected with a Lowrance X-16 were paired with range measurements taken from a Bushnell Laser Ranger (± 1 m accuracy) aimed at a fixed target on shore. When bottom profile information is combined with vertical tilt information from the DIDSON's internal orientation sensor, a detailed visualization of how the acoustic beam insonifies the water column above the bottom substrate can be generated (Figure 5). Each time a transducer was moved, new measurements of the transducer height above the bottom substrate and its position relative to a fixed shore location were updated in an Excel worksheet so that beam coverage at the new location could be evaluated.

Before 2001, the right- and left-bank transducers were deployed directly across the river from each other, and complete beam coverage for the entire middle portion of the river was

² Product names used in this publication are included for completeness but do not constitute product endorsement.

accomplished by extending the counting range for both banks to the thalweg (the line delimiting the lowest points along the length of the river bed). Under these conditions, we could be relatively certain that the entire middle portion of the river was insonified. In 2001, river bottom profiles indicated that improved beam coverage (in the vertical plane) could be attained on the left bank by moving the transducer approximately 35 m downstream of its original location (Miller et al. 2003). The left-bank transducer has been deployed at this location since 2001. Because of the offset deployment of the right- and left-bank transducers (Figure 3), it is difficult to determine if there is complete beam coverage (Miller et al. 2004). For this reason, it is possible that some fish migrating near the thalweg (making up a small fraction of the inriver run) are double-counted or missed entirely.

Sampling Procedure

A systematic sample design (Cochran 1977) was used to estimate fish passage between each transducer and the river thalweg. Four separate range strata were sampled on each bank (3.3–8.3 m, 8.3–13.3 m, 13.3–23.3 m, and 23.3–33.3 m; Figure 6). The DIDSON was programmed to sample each stratum systematically for 10 min per hour according to the schedule outlined in Figure 7. This routine was followed 24 hours per day and 7 days per week unless a transducer on one or both banks was inoperable.

A test of the systematic sample design in 1999 found no significant difference between estimates of Chinook salmon passage obtained using 1-hour counts and estimates obtained by extrapolating 20-minute counts to 1 hour (Miller et al. 2002). Systematic 10-minute counts have been used for decades at counting towers elsewhere in Alaska and have been found to provide accurate estimates of passage (Reynolds et al. 2007; Xie and Martens 2014).

Because fish passage rates are related to tides (Eggers et al. 1995), tide stage was recorded at the top of each hour and at 30 minutes past each hour. Tide stage was determined using water level measurements taken from an AIM 2000 depth sensor attached to the right-bank DIDSON mount.

Data Collection Parameters

The autofocus feature was enabled so that the sonar automatically set the lens focus to the midrange of the selected display window (e.g., for a window length of 10 m that started at 15 m, the focus range would be 20 m; Appendix A1). The frame rate (frames per second, or fps) differed by stratum: 10 fps for 3.3–8.3 m and 8.3–13.3 m strata, 7 fps for 13.3–23.3 m strata, and 5 fps for 23.3–33.3 m strata. Long-range strata require more time for the transmitted sound to return, necessitating slower frame rates.

Manual DIDSON Fish Length Measurements

Software included with the DIDSON system (Control and Display software Version 5.25) was used to count and measure fish from DIDSON images. Electronic echograms provided the means to manually count, track, and size individual fish (Figure 6). Noise from stationary structures was removed from the images using Sound Metric Corporation's algorithm for dynamic background removal. Fish traces displayed on the echogram could also be displayed in video mode through a toggle function (Figure 6). In video mode, technicians used the manual measuring tools to estimate the DIDSON-based length (DL) for each fish. Date, time, frame number, range, and direction of travel were also recorded for each free-swimming fish. Details regarding which fish to measure and whether or not to record direction of travel differed depending upon rate of fish

passage and level of staffing. On a given day, one of the following 2 sampling protocols was selected to guide processing and analysis of the data³.

Standard (STD) Sampling Protocol

The standard (STD) sampling protocol, used 16 May–03 July, was as follows:

- 1) Length was measured from the DIDSON image for all salmon-shaped fish greater than or equal to 40 cm (DL).
- 2) Direction of travel was recorded for each measured fish.

The 40 cm threshold approximately separates salmon from nonsalmon species. It also corresponds approximately to the smallest fish gilled in the inriver netting project (Perschbacher 2014). Fish measuring less than 40 cm were omitted from further calculations. Flatfish, seals, and beluga whales (*Delphinapterus leucas*) were not recorded.

Fast Track (FT) Sampling Protocol

During most of the late run (4 July–15 August), the following “fast track” (FT) sampling protocol was used:

- 1) Length was measured for all large salmon-shaped fish greater than or equal to 75 cm DL.
- 2) Length was also measured for a subset of medium salmon-shaped fish greater than or equal to 40 cm and up to 75 cm DL. The remaining fish greater than or equal to 40 cm and less than 75 cm were counted but not measured.
- 3) Direction of travel was recorded for each measured fish.

Under both protocols, any fish appearing in a DIDSON image was a candidate for counting and measuring. That is, there was no requirement that the fish cross the center of the beam. Additional details on the procedures and software settings used to obtain manual fish length measurements can be found in Burwen et al. (2010) and in Appendices A5–A8.

DATA ANALYSIS

DIDSON data were used to generate multiple estimates of fish passage, detailed below. Except where otherwise stated, all estimates apply to fish migrating upstream in a midriver corridor greater than 3 m from both the left- and right-bank transducers. Note that this corridor is 19 m wider than that formerly covered by split-beam sonar, which was greater than 15 m from the right-bank transducer and greater than 10 m from the left-bank transducer.

Fish longer than 40 cm are referred to generically as “salmon” in this report. A minimum threshold of 40 cm includes virtually all Chinook salmon and effectively excludes nonsalmon species. For example, none of 255 Chinook salmon caught in gillnets at RM 8.6 in 2013 were smaller than 40 cm (16 inches; Perschbacher 2015). The proportion of fish over 40 cm that were not salmon is not known because nonsalmon species were not measured; however, the proportion was very small.

³ A third sampling protocol (not described here) has sometimes been used on even-numbered years when large numbers of milling pink salmon can be present (Key et al. 2016).

Midriver Salmon Passage

The DIDSON generally operated 10 minutes per hour for each spatial stratum, 24 hours per day. The number of salmon-sized fish y passing upstream, midriver between the transducers, during day i was estimated as follows:

$$\hat{y}_i = 24 \hat{\bar{y}}_i \quad (1)$$

where

$$\hat{\bar{y}}_i = \frac{1}{n_i} \sum_{j=1}^{n_i} \hat{y}_{ij} \quad (2)$$

n_i is the number of hours (j) during which fish passage was estimated for day i , and

$$\hat{y}_{ij} = \sum_{k=1}^2 \hat{y}_{ijk} \quad (3)$$

where k is bank. The quantity \hat{y}_{ijk} is upstream midriver fish passage on bank k during hour j of day i and is estimated as

$$\hat{y}_{ijk} = \sum_{s=1}^4 \hat{y}_{ijks} \quad (4)$$

where s is stratum. The quantity \hat{y}_{ijks} is upstream midriver fish passage for stratum s of bank k during hour j of day i , which is estimated as

$$\hat{y}_{ijks} = \frac{60}{m_{ijks}} c_{ijks} \quad (5)$$

where

m_{ijks} = number of minutes (usually 10) sampled for stratum s of bank k during hour j of day i , and

c_{ijks} = number of upstream bound fish greater than or equal to 40 cm in stratum s of bank k during hour j of day i .

When samples were missed due to equipment malfunction on one bank, passage on the nonfunctional bank k' was estimated from passage on the functional bank k as follows:

$$\hat{y}_{ijk'} = \hat{R}_{ikt} \hat{y}_{ijk} \quad (6)$$

where the estimated bank-to-bank ratio \hat{R}_{ikt} for day i and tide stage t was calculated by pooling counts from all hours at tide stage t (set J_t) during the previous 2 days (to ensure adequate sample size) as follows:

$$\hat{R}_{ikt} = \frac{\sum_{j \in J_t} \hat{y}_{(i-2)jk'} + \sum_{j \in J_t} \hat{y}_{(i-1)jk'}}{\sum_{j \in J_t} \hat{y}_{(i-2)jk} + \sum_{j \in J_t} \hat{y}_{(i-1)jk}} \quad (7)$$

The variance of the daily estimates \hat{y}_i , due to systematic sampling in time, was approximated (successive difference model, Wolter 1985) with adjustments for missing data as follows:

$$\hat{V}[\hat{y}_i] \cong 24^2(1-f) \frac{\sum_{j=2}^{24} \phi_{ij} \phi_{i(j-1)} (\hat{y}_{ij} - \hat{y}_{i(j-1)})^2}{2 \sum_{j=1}^{24} \phi_{ij} \sum_{j=2}^{24} \phi_{ij} \phi_{i(j-1)}} \quad (8)$$

where f is the sampling fraction (proportion of time sampled daily, usually 0.17), and ϕ_{ij} is 1 if \hat{y}_{ij} exists for hour j of day i , or 0 if not. This variance is an assessment of the uncertainty due to subsampling (counting fish for 10 minutes per hour and expanding). It is conservative in the sense that it has been shown to overestimate the true uncertainty when applied to salmon passage data (Reynolds et al. 2007; Xie and Martens 2014).

The estimate of total upstream midriver fish passage during the period of sonar operation, and its variance, was the sum of all daily estimates:

$$\hat{Y} = \sum_i \hat{y}_i \quad (9)$$

and

$$\hat{V}[\hat{Y}] = \sum_i \hat{V}[\hat{y}_i]. \quad (10)$$

Midriver Large Fish Passage

The estimated number of large fish passing upstream in midriver during day i was calculated following Equations 1–10 after redefining c_{ijks} in Equation 5 to be the number of upstream-bound fish greater than 3 m from the right- and left-bank transducers and equal to or exceeding X cm in length as measured by the DIDSON for the sample of stratum s on bank k during hour j of day i , where X is 75, 80, or 90 cm.

Midriver Chinook Salmon Passage

The number of Chinook salmon passing upstream in midriver on day i was estimated by multiplying the sonar-based midriver salmon passage estimate by a sonar- and netting-based estimate of the proportion of salmon that were Chinook salmon:

$$\hat{z}_i = \hat{y}_i \hat{\pi}_{Ci} \quad (11)$$

where y_i is upstream passage of salmon-sized fish between and at least 3 m from both the left-bank transducer and right-bank transducers (estimated using Equation 1), and $\hat{\pi}_{Ci}$ is the estimated proportion of salmon passing in midriver that were Chinook salmon, obtained by fitting a statistical “mixture” model to DIDSON length data, gillnet catches, and tethered fish data. The DIDSON length mixture model (DLMM) is described in Appendices B1–B3; WinBUGS code is provided in Appendices B4–B6, and technical details are summarized in Appendix B7.

Variance estimates follow Goodman (1960):

$$\hat{V}(\hat{z}_i) = \hat{y}_i^2 \hat{V}(\hat{\pi}_{Ci}) + \hat{\pi}_{Ci}^2 \hat{V}(\hat{y}_i) - \hat{V}(\hat{\pi}_{Ci}) \hat{V}(\hat{y}_i). \quad (12)$$

Cumulative estimates were obtained by summing daily estimates and variances.

Net-apportioned Chinook Salmon Index

The “net-apportioned” daily index of Chinook salmon passage is the product of a sonar-based passage estimate and a netting-derived estimate of species composition:

$$\hat{y}_{NETi} = \hat{y}_{SBi} \hat{\pi}_{NETi} \quad (13)$$

with variance

$$\hat{V}(\hat{y}_{NETi}) = \hat{y}_{SBi}^2 \hat{V}(\hat{\pi}_{NETi}) + \hat{\pi}_{NETi}^2 \hat{V}(\hat{y}_{SBi}) - \hat{V}(\hat{\pi}_{NETi}) \hat{V}(\hat{y}_{SBi}) \quad (14)$$

where y_{SBi} is upstream passage of salmon-sized fish greater than 10 m from the left-bank transducer and greater than 15 m from the right-bank transducer (formerly composing the split-beam sonar corridor), and $\hat{\pi}_{NETi}$ is the estimated proportion of drift gillnet catches that were Chinook salmon (Perschbacher 2015).

RESULTS

Long-range high-resolution DIDSON units were deployed from both banks and sampled the midsection of the river for 92 days (16 May–15 August) in 2013. Salmon passage was successfully estimated in 98% of both early-run and late-run samples.

SIZE DISTRIBUTION AND SPECIES COMPOSITION

Small fish predominated in both the early and late runs as evidenced by large left-hand modes in the DIDSON length (DL) frequency distributions (Figure 8, top panels). The modes of the DL distributions line up well with mid eye to tail fork (METF) length distributions from salmon measured by the inriver netting project (Figure 8, bottom panels). The DL distributions are broader than the corresponding METF distributions because there is greater error associated with measuring length from the DIDSON images.

The shapes of the frequency distributions in Figure 8 suggest that fish measuring greater than approximately 75 cm DL are probably Chinook salmon. Thus, from these data, “large Chinook salmon” can be defined as fish greater than or equal to 75 cm DL. Although the species of individual fish cannot be determined with certainty from DIDSON images, probably very few fish greater than 75 cm DL were *not* Chinook salmon.

SPATIAL AND TEMPORAL DISTRIBUTION

During the early run, salmon of all sizes favored the left bank of the insonified zone (Figure 9). During the late run, large Chinook salmon continued to favor the left bank, but small salmon favored the right bank (Figure 9). During both the early and late runs, most (64% and 61% respectively) upstream bound large ($DL \geq 75$ cm) Chinook salmon were observed from the left-bank transducer (Table 2).

Distribution by range strata (3–8 m, 8–13 m, 13–23 m, and 23–33 m) was 22%, 15%, 28%, and 35%, respectively in the early run and 17%, 19%, 30%, and 35%, respectively during the late run (derived from summed values for left and right banks in Table 2). The temporal distribution of large Chinook salmon among tide stages differed by run, from 33%, 47%, and 19% on the rising, falling, and low tides, respectively during the early run to 52%, 34%, and 15%, respectively during the late run (Table 2, last column). During 16 May to 15 August, the natural distribution of tide stages was 33% rising, 41% falling, and 25% low. Comparing this to the tidal distribution of salmon (Table 2) indicates that disproportionately large fractions of large Chinook salmon migrated past the site during the falling tide in the early run, and during the rising tide in the late run.

The proportion of all upstream-bound salmon that were classified as large Chinook salmon (≥ 75 cm DL) varied by run, bank, range stratum, and tide stage (Table 3). A smaller proportion of salmon were large Chinook salmon in the early run (3.8%) than in the late run (5.1%).

During the early run, the highest proportions of large fish occurred in the center of the river (left and right bank 23–33 m strata) and in the 3–8 m stratum on the left bank (Table 3). During the late run, when small salmon favored the right bank (Figure 9), relatively more salmon were large Chinook salmon on the left bank (5.9%) than on the right bank (4.2%), with the lowest fraction (3.5%) occurring in the nearshore right-bank stratum.

During the early run, upstream moving salmon that passed during rising tide had the highest fraction of large Chinook salmon (4.3%), followed by the falling tide (3.7%), and the low tide (3.6%) (Table 3). During the late run, fish migrating during rising tide were composed of 7.0% large Chinook salmon, followed by 5.5% during the low tide, and 3.6% during the falling tide (Table 3).

Spatial and temporal patterns of migration of small, medium, and large salmon are displayed relative to tide stage in Appendices C1–C7. In general, Chinook salmon greater than or equal to 75 cm DL were interspersed throughout the sampled range and were only mildly clustered in space and time. Smaller salmon exhibited more clustering than did large Chinook salmon, and their migration timing was strongly influenced by the tide cycle.

DIRECTION OF TRAVEL

Among fish that were greater than or equal to 75 cm DL, 94.3% were upstream bound in the early run, and 97.4% were upstream bound in the late run (Appendices D1 and D2). Daily percentages of fish greater than or equal to 75 cm DL that were upstream bound, ranged from 0% (27 May; 0 of 2 fish) to 100% (many days).

MIDRIVER SALMON PASSAGE

Daily DIDSON estimates of upstream salmon passage totaled 26,256 (SE 564) for the early run (Table 4) and 313,277 (SE 6,917) for the late run (Table 5).

MIDRIVER CHINOOK SALMON PASSAGE

Daily proportions of upstream-bound salmon that were Chinook salmon were estimated by fitting a mixture model to fish length measurements from the DIDSON and netting data (Appendices B1–B7). These proportions were multiplied by DIDSON estimates of upstream salmon passage to produce DLMM estimates of upstream Chinook salmon passage: 1,439

(SE 138) Chinook salmon during the early run (16 May–30 June; Table 4) and 15,185 (SE 566) during the late run (1 July–15 August; Table 5).

The DLMM also produced daily estimates of Chinook salmon age composition (Tables 6 and 7). These estimates incorporated length information from DIDSON as well from inriver gillnet catches. All DIDSON-based estimates are germane to a midriver water column located between and at least 3 m from the transducers at RM 8.6.

MIDRIVER LARGE FISH PASSAGE

Daily “threshold” estimates of fish equal to or exceeding DIDSON lengths of 75 cm, 80 cm, and 90 cm are tabulated in Appendices E1 and E2. A DIDSON length of 90 cm is approximately midway between the average lengths of age-5 and age-6 (total age from spawning event) Chinook salmon.

NET-APPORTIONED INDEX OF CHINOOK SALMON PASSAGE

Net-apportioned estimates of upstream Chinook salmon passage were 2,176 (SE 312) fish during the early run and 17,747 (SE 1,557) fish during the late run (Appendices F1 and F2).

DISCUSSION

NET-APPORTIONED INDEX OF CHINOOK SALMON PASSAGE

It is important to note that DIDSON generally detects and resolves more fish than split-beam sonar. Therefore the net-apportioned estimates based on DIDSON counts are greater than what would have been estimated using the 2002–2011 versions of net-apportioned estimates based on split-beam sonar. Any comparison between 2013 and 2002–2011 versions of net-apportioned estimates must take this difference into account. See Miller et al. (2013: Figure 26) and Miller et al. (2014: Figure 16) for a quantification of this difference. Finally, comparisons of net-apportioned estimates from 2012 to 2013 versus 2002 to 2011 will be imperfect because in 2012–2013 the inriver netting program sampled the river corridor insonified by the DIDSON (Perschbacher 2014, 2015) rather than the corridor formerly insonified by the split-beam sonar.

COMPARISON OF DIDSON WITH OTHER DAILY INDICES OF CHINOOK SALMON PASSAGE

In 2013, daily values of inriver gillnetting CPUE, net-apportioned estimates, and sport fishery CPUE tracked DIDSON estimates of Chinook salmon passage with varying degrees of (visually compared but unmeasured) congruity (Figures 10, 11, and 12). As more index data are collected concurrent with DIDSON data, it will be possible to more thoroughly evaluate their strengths and weaknesses and to identify confounding influences.

EARLY RUN SONAR COMPARED TO WEIR COUNTS ON UPRIVER TRIBUTARIES

Using a state-space model (Fleischman and McKinley 2013; McKinley and Fleischman 2013), which estimated that the proportion of Chinook salmon migrating midriver and detected by sonar and nets at RM 8.6 was 0.65 during the early run, the spatially expanded DLMM estimate of early-run Chinook salmon passage was 2,230 (Table 4 sum multiplied by $1/0.65 = 1.55$). The expanded DLMM estimate of early-run Chinook salmon passage (2,230) is not large enough to

explain the 2013 weir counts at the Funny and Killey rivers (2,908; Gates and Boersma 2014; Boersma and Gates 2014). This early-run shortfall at the sonar can be ascribed almost entirely to small Chinook salmon that managed to evade detection at RM 8.6. The estimated DIDSON count of small (<75 cm DL) Chinook salmon passing RM 8.6 during the 2013 early run was only 682⁴, compared to approximately 2,095 (<74 cm METF length) Chinook salmon that passed the Funny and Killey river weirs (derived from data reported by Gates and Boersma [2014] and Boersma and Gates [2014]). The estimated DIDSON count of large (≥ 75 cm DL) Chinook salmon (Appendix E, 999 midriver spatially expanded to 1,548) was only slightly smaller than ARIS estimates at RM 13.7 (1,724) (Miller et al. 2016). Apparently, many small Chinook salmon migrated undetected between the transducers and shore during the 2013 early run. Experimental netting at RM 8.6 found higher catch rates near shore than in midriver during the early run, and Chinook salmon caught near shore were smaller than those caught midriver during the early run (Perschbacher 2015). During the late run, nearshore catch rates dropped and nearshore migrants were similar in size to midriver migrants.

Sonar assessment of small Chinook salmon during the Kenai River early run clearly presents major challenges. See Miller et al. (2016) and Miller et al. (*In prep*) for continued discussion on this topic.

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⁴ 1,439 Chinook salmon (Table 4) minus 999 Chinook salmon 75 cm DL or greater (Appendix E) equals 440 Chinook salmon less than 75 cm DL. Multiplying by the 1.55 spatial expansion factor yields an estimated 682 small Chinook salmon. A DIDSON length of 75 cm is approximately equivalent to 74 cm METF length (Miller et al 2016).

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TABLES

Table 1.–Components of the DIDSON sonar system used in 2013.

System component	Description
Sounder	DIDSON-LR operating at 1.2 MHz (one for each bank)
Orientation sensor	Honeywell Truepoint Compass (internal)
Lens	High Resolution Lens Assembly with $\sim 3^\circ \times 15^\circ$ beam pattern
Data collection computer	Dell Latitude E6500 laptop computer (one for each sonar)
Remote pan-and-tilt aiming controller	Remote Ocean Systems Model PTC-1 Pan-and-tilt Controller (right bank)
Remote pan-and-tilt aiming unit	Remote Ocean Systems Model P-25 Remote Pan-and-tilt Unit (right bank) Sound Metrics X2 rotator – controlled via DIDSON software (left bank)
Heading and angular measurement device	JASCO Research Ltd. AIM-2000 (provided depth and temperature readings – right bank)

Table 2.—Percentage of upstream-bound large Chinook salmon (DIDSON length ≥ 75 cm) by riverbank, range stratum (distance from transducer), and tide stage sampled by DIDSON at RM 8.6 for the 2013 early and late runs.

Run	Tide stage	Left bank					Right bank					Both banks
		Range stratum				All strata	Range stratum				All strata	
		3–8 m	8–13 m	13–23 m	23–33 m		3–8 m	8–13 m	13–23 m	23–33 m		
Early												
	Rising	5	2	6	6	18	0	2	5	9	15	33
	Falling	9	5	7	10	30	2	2	6	6	17	47
	Low	6	2	4	4	16	1	1	1	1	4	19
	All stages	19	10	16	19	64	4	5	12	16	36	100
Late												
	Rising	5	6	9	9	30	3	4	6	9	22	52
	Falling	3	4	7	8	22	2	2	4	5	12	34
	Low	3	2	3	3	10	1	2	2	1	5	15
	All stages	11	12	18	20	61	6	7	12	15	39	100

Note: Columns may not sum due to rounding.

Table 3.—Percentage of all upstream-bound salmon that were classified as large Chinook salmon (DIDSON length ≥ 75 cm) by riverbank, range stratum (distance from transducer), and tide stage at RM 8.6 for the 2013 early and late runs.

Run	Tide stage	Left bank					Right bank					Both banks
		Range stratum				All strata	Range stratum				All strata	
		3–8 m	8–13 m	13–23 m	23–33 m		3–8 m	8–13 m	13–23 m	23–33 m		
Early												
	Rising	5.5	2.5	3.2	4.7	3.9	0.0	3.5	5.1	7.3	4.9	4.3
	Falling	6.3	3.0	2.2	4.9	3.8	3.7	3.0	3.9	3.4	3.5	3.7
	Low	5.6	2.6	3.3	4.0	3.8	7.4	2.5	1.6	2.8	3.0	3.6
	All stages	5.8	2.7	2.7	4.6	3.8	2.9	3.1	4.0	4.7	3.9	3.8
Late												
	Rising	7.6	8.5	7.9	7.9	7.9	4.7	4.8	5.8	7.7	6.0	7.0
	Falling	3.5	3.9	4.4	4.8	4.3	2.2	2.3	2.8	3.7	2.9	3.6
	Low	8.6	7.4	6.0	6.2	6.9	3.7	4.6	4.3	3.5	4.1	5.5
	All stages	5.7	6.0	5.9	6.1	5.9	3.5	3.6	4.1	5.2	4.2	5.1

Note: Columns may not sum due to rounding.

Table 4.–DIDSON-based estimates (without spatial expansion) of upstream salmon passage, DL mixture model (DLMM) proportion of salmon that were Chinook salmon, and DLMM-estimated upstream Chinook salmon passage, RM 8.6 Kenai River, early run, 2013.

Date	DIDSON upstream salmon		DLMM Chinook salmon		DLMM Chinook salmon		
	Passage	SE	Proportion	SE	Passage	SE	CV
16 May	0	0			0	0	
17 May	6	5	0.551	0.288	3	3	0.97
18 May	24	9	0.306	0.256	7	6	0.90
19 May	24	8	0.035	0.104	1	2	2.38
20 May	30	12	0.330	0.231	10	7	0.75
21 May	60	13	0.209	0.125	13	8	0.60
22 May	193	30	0.190	0.080	37	16	0.44
23 May	211	43	0.132	0.068	28	15	0.54
24 May	185	37	0.127	0.098	24	18	0.77
25 May	127	36	0.135	0.103	17	13	0.79
26 May	148	31	0.054	0.051	8	8	0.95
27 May	265	41	0.003	0.011	1	3	2.85
28 May	223	36	0.004	0.011	1	2	2.42
29 May	247	44	0.005	0.017	1	4	4.04
30 May	200	46	0.054	0.062	11	12	1.12
31 May	362	45	0.002	0.008	1	3	2.97
1 Jun	923	104	0.032	0.017	30	16	0.54
2 Jun	868	83	0.022	0.018	19	16	0.83
3 Jun	464	64	0.058	0.047	27	22	0.81
4 Jun	567	49	0.010	0.019	6	11	1.82
5 Jun	291	50	0.138	0.084	40	25	0.63
6 Jun	464	82	0.036	0.033	17	15	0.90
7 Jun	615	82	0.040	0.031	24	19	0.79
8 Jun	434	57	0.190	0.080	83	36	0.43
9 Jun	327	55	0.074	0.049	24	16	0.69
10 Jun	283	42	0.080	0.057	23	16	0.71
11 Jun	338	49	0.067	0.049	23	17	0.73
12 Jun	488	63	0.047	0.033	23	16	0.71
13 Jun	790	71	0.078	0.035	61	28	0.46
14 Jun	1,182	82	0.049	0.021	58	26	0.44
15 Jun	995	85	0.032	0.020	32	20	0.63
16 Jun	610	73	0.061	0.031	37	20	0.53
17 Jun	632	58	0.069	0.040	44	25	0.57
18 Jun	371	45	0.008	0.020	3	7	2.42
19 Jun	498	63	0.091	0.057	45	29	0.64

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Table 4.–Page 2 of 2.

Date	DIDSON upstream salmon		DLMM Chinook salmon		DLMM Chinook salmon		
	Passage	SE	Proportion	SE	Passage	SE	CV
20 Jun	271	40	0.060	0.045	16	12	0.77
21 Jun	465	42	0.113	0.045	53	21	0.40
22 Jun	482	49	0.089	0.037	43	18	0.43
23 Jun	307	40	0.077	0.044	24	14	0.58
24 Jun	494	94	0.046	0.031	23	16	0.69
25 Jun	734	84	0.035	0.021	25	16	0.62
26 Jun	705	71	0.059	0.031	41	22	0.54
27 Jun	1,019	105	0.036	0.016	37	17	0.46
28 Jun	2,617	155	0.026	0.009	68	24	0.36
29 Jun	3,268	333	0.043	0.013	141	45	0.32
30 Jun	2,449	198	0.076	0.025	186	63	0.34
Total	26,256	564			1,439	138	0.10

Table 5.—DIDSON-based estimates (without spatial expansion) of upstream salmon passage, DL mixture model (DLMM) proportion of salmon that were Chinook salmon, and DLMM-estimated upstream Chinook salmon passage, RM 8.6 Kenai River, late run, 2013.

Date	DIDSON upstream salmon		DLMM Chinook salmon		DLMM Chinook salmon		
	Passage	SE	Proportion	SE	Passage	SE	CV
1 Jul	2,583	255	0.085	0.026	219	70	0.32
2 Jul	1,761	171	0.121	0.034	213	63	0.30
3 Jul	5,342	368	0.040	0.013	215	72	0.33
4 Jul	6,995	463	0.029	0.009	199	64	0.32
5 Jul	4,492	365	0.045	0.012	201	54	0.27
6 Jul	3,184	289	0.044	0.015	140	50	0.35
7 Jul	2,177	156	0.064	0.021	140	46	0.33
8 Jul	3,497	258	0.042	0.014	146	48	0.33
9 Jul	8,641	848	0.035	0.008	302	76	0.25
10 Jul	16,589	1,189	0.030	0.006	502	112	0.22
11 Jul	11,567	1,074	0.035	0.007	406	87	0.22
12 Jul	2,997	312	0.084	0.023	252	72	0.29
13 Jul	10,448	996	0.045	0.009	475	104	0.22
14 Jul	10,338	1,084	0.085	0.016	877	186	0.21
15 Jul	17,388	3,757	0.026	0.005	459	131	0.29
16 Jul	22,618	2,849	0.032	0.006	718	156	0.22
17 Jul	18,866	2,066	0.030	0.006	571	121	0.21
18 Jul	20,334	2,310	0.029	0.006	590	131	0.22
19 Jul	22,400	1,878	0.017	0.004	372	84	0.23
20 Jul	13,690	820	0.017	0.005	234	69	0.30
21 Jul	5,421	406	0.037	0.010	201	57	0.28
22 Jul	3,326	394	0.100	0.024	334	88	0.26
23 Jul	5,119	370	0.081	0.019	417	102	0.24
24 Jul	3,211	284	0.086	0.021	276	71	0.26
25 Jul	4,007	313	0.106	0.025	424	103	0.24
26 Jul	8,397	703	0.066	0.013	554	116	0.21
27 Jul	9,953	1,332	0.036	0.006	358	80	0.22
28 Jul	4,829	485	0.072	0.013	348	72	0.21
29 Jul	5,146	680	0.121	0.015	622	113	0.18
30 Jul	3,054	222	0.172	0.022	526	78	0.15
31 Jul	3,518	291	0.137	0.020	482	82	0.17

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Table 5.–Page 2 of 2.

Date	DIDSON upstream salmon		DLMM Chinook salmon		DLMM Chinook salmon		
	Passage	SE	Proportion	SE	Passage	SE	CV
1 Aug	3,109	286	0.130	0.020	404	73	0.18
2 Aug	1,685	120	0.154	0.031	259	56	0.22
3 Aug	2,536	218	0.148	0.029	375	80	0.21
4 Aug	2,802	302	0.117	0.021	328	69	0.21
5 Aug	3,105	341	0.073	0.015	228	52	0.23
6 Aug	2,916	187	0.076	0.016	221	49	0.22
7 Aug	2,415	89	0.066	0.015	161	37	0.23
8 Aug	2,905	173	0.049	0.011	141	33	0.24
9 Aug	4,384	306	0.037	0.009	163	43	0.26
10 Aug	4,500	472	0.044	0.010	200	50	0.25
11 Aug	4,233	480	0.043	0.010	184	46	0.25
12 Aug	4,982	582	0.033	0.009	165	51	0.31
13 Aug	4,554	509	0.049	0.011	222	54	0.24
14 Aug	4,094	335	0.060	0.012	245	51	0.21
15 Aug	3,169	310	0.037	0.011	116	36	0.31
Total	313,277	6,917			15,185	566	0.04

Note: All estimates are of upstream-bound fish in midriver between and at least 3 m from the transducer.

Table 6.—Daily estimates of Chinook salmon age composition derived from fitting a mixture model to length measurements from DIDSON and inriver gillnet catches, RM 8.6 Kenai River, early run, 2013.

Date	Ages 3 and 4		Age 5		Ages 6 and 7	
	Proportion	SE	Proportion	SE	Proportion	SE
16 May						
17 May	0.17	0.19	0.17	0.20	0.66	0.24
18 May	0.25	0.24	0.20	0.23	0.55	0.28
19 May	0.17	0.19	0.19	0.22	0.64	0.26
20 May	0.13	0.15	0.13	0.15	0.73	0.19
21 May	0.09	0.11	0.08	0.10	0.83	0.14
22 May	0.10	0.12	0.11	0.13	0.79	0.16
23 May	0.11	0.13	0.20	0.18	0.69	0.20
24 May	0.16	0.18	0.23	0.20	0.61	0.23
25 May	0.13	0.15	0.16	0.16	0.71	0.20
26 May	0.16	0.18	0.11	0.14	0.73	0.21
27 May	0.26	0.25	0.23	0.25	0.51	0.29
28 May	0.26	0.25	0.19	0.21	0.55	0.28
29 May	0.26	0.26	0.19	0.21	0.54	0.28
30 May	0.26	0.25	0.15	0.18	0.59	0.26
31 May	0.27	0.26	0.19	0.22	0.54	0.28
1 Jun	0.15	0.17	0.23	0.21	0.62	0.23
2 Jun	0.19	0.20	0.21	0.22	0.61	0.26
3 Jun	0.48	0.20	0.08	0.11	0.44	0.20
4 Jun	0.58	0.17	0.31	0.17	0.12	0.13
5 Jun	0.55	0.13	0.29	0.14	0.16	0.12
6 Jun	0.50	0.13	0.18	0.12	0.32	0.12
7 Jun	0.50	0.13	0.26	0.13	0.24	0.12
8 Jun	0.46	0.12	0.17	0.11	0.37	0.12
9 Jun	0.47	0.12	0.27	0.12	0.26	0.11
10 Jun	0.40	0.12	0.33	0.13	0.27	0.11
11 Jun	0.41	0.14	0.29	0.15	0.30	0.12
12 Jun	0.40	0.16	0.28	0.16	0.32	0.13
13 Jun	0.41	0.15	0.30	0.19	0.29	0.16
14 Jun	0.43	0.14	0.32	0.17	0.26	0.13
15 Jun	0.51	0.16	0.31	0.17	0.18	0.11
16 Jun	0.37	0.14	0.48	0.18	0.15	0.13
17 Jun	0.48	0.16	0.23	0.17	0.29	0.14
18 Jun	0.31	0.14	0.36	0.20	0.33	0.18
19 Jun	0.25	0.15	0.44	0.19	0.31	0.16
20 Jun	0.28	0.15	0.38	0.19	0.34	0.16

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Table 6.–Page 2 of 2.

Date	Ages 3 and 4		Age 5		Ages 6 and 7	
	Proportion	SE	Proportion	SE	Proportion	SE
21 Jun	0.20	0.16	0.38	0.18	0.42	0.15
22 Jun	0.14	0.13	0.36	0.18	0.49	0.17
23 Jun	0.15	0.14	0.41	0.20	0.43	0.18
24 Jun	0.08	0.10	0.52	0.19	0.41	0.18
25 Jun	0.08	0.10	0.59	0.18	0.33	0.17
26 Jun	0.14	0.10	0.51	0.16	0.35	0.15
27 Jun	0.13	0.09	0.44	0.17	0.43	0.17
28 Jun	0.18	0.10	0.46	0.14	0.36	0.13
29 Jun	0.36	0.12	0.24	0.13	0.40	0.12
30 Jun	0.53	0.11	0.19	0.10	0.29	0.09
Weighted mean	0.33		0.29		0.38	

Note: Estimates apply to upstream-bound fish in midriver between and at least 3 m from the transducers. In the mixture model, ages 3 and 4 are pooled, as are ages 6 and 7. Means are weighted by daily DLMM estimates.

Table 7.—Daily estimates of Chinook salmon age composition derived from fitting a mixture model to length measurements from DIDSON and inriver gillnet catches, RM 8.6 Kenai River, late run, 2013.

Date	Ages 3 and 4		Age 5		Ages 6 and 7	
	Proportion	SE	Proportion	SE	Proportion	SE
1 Jul	0.53	0.11	0.11	0.08	0.37	0.09
2 Jul	0.56	0.1	0.11	0.07	0.33	0.08
3 Jul	0.7	0.09	0.04	0.05	0.26	0.08
4 Jul	0.58	0.09	0.07	0.07	0.35	0.1
5 Jul	0.56	0.09	0.05	0.05	0.39	0.08
6 Jul	0.6	0.08	0.02	0.02	0.39	0.08
7 Jul	0.49	0.09	0.03	0.04	0.48	0.09
8 Jul	0.53	0.09	0.03	0.04	0.44	0.08
9 Jul	0.47	0.08	0.02	0.02	0.52	0.08
10 Jul	0.47	0.09	0.08	0.06	0.44	0.08
11 Jul	0.47	0.08	0.05	0.05	0.48	0.07
12 Jul	0.49	0.1	0.11	0.08	0.4	0.07
13 Jul	0.39	0.09	0.09	0.06	0.52	0.08
14 Jul	0.46	0.09	0.07	0.06	0.48	0.07
15 Jul	0.41	0.08	0.08	0.06	0.51	0.08
16 Jul	0.4	0.09	0.17	0.08	0.43	0.08
17 Jul	0.41	0.09	0.07	0.06	0.52	0.08
18 Jul	0.36	0.1	0.18	0.12	0.46	0.12
19 Jul	0.38	0.09	0.02	0.02	0.6	0.09
20 Jul	0.42	0.1	0.05	0.07	0.53	0.11
21 Jul	0.38	0.1	0.06	0.07	0.56	0.1
22 Jul	0.42	0.1	0.06	0.07	0.52	0.1
23 Jul	0.49	0.1	0.08	0.08	0.43	0.09
24 Jul	0.44	0.1	0.12	0.11	0.44	0.11
25 Jul	0.44	0.1	0.07	0.07	0.49	0.09
26 Jul	0.33	0.09	0.05	0.06	0.62	0.09
27 Jul	0.21	0.08	0.32	0.11	0.48	0.11
28 Jul	0.25	0.08	0.08	0.08	0.67	0.09
29 Jul	0.21	0.06	0.05	0.05	0.74	0.07
30 Jul	0.18	0.06	0.07	0.07	0.75	0.08
31 Jul	0.2	0.07	0.07	0.07	0.73	0.09

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Table 7.–Page 2 of 2.

Date	Ages 3 and 4		Age 5		Ages 6 and 7	
	Proportion	SE	Proportion	SE	Proportion	SE
1 Aug	0.19	0.07	0.29	0.11	0.52	0.11
2 Aug	0.23	0.08	0.20	0.12	0.57	0.13
3 Aug	0.25	0.09	0.08	0.08	0.67	0.11
4 Aug	0.23	0.08	0.06	0.07	0.71	0.10
5 Aug	0.18	0.08	0.07	0.06	0.75	0.09
6 Aug	0.22	0.09	0.08	0.07	0.70	0.10
7 Aug	0.17	0.08	0.14	0.11	0.69	0.12
8 Aug	0.13	0.07	0.30	0.18	0.57	0.18
9 Aug	0.18	0.09	0.15	0.13	0.67	0.13
10 Aug	0.20	0.10	0.21	0.15	0.59	0.15
11 Aug	0.12	0.09	0.36	0.16	0.52	0.16
12 Aug	0.13	0.09	0.28	0.18	0.59	0.18
13 Aug	0.07	0.09	0.35	0.13	0.58	0.12
14 Aug	0.08	0.09	0.26	0.17	0.66	0.16
15 Aug	0.10	0.11	0.28	0.15	0.62	0.15
Weighted mean	0.35		0.11		0.54	

Note: Estimates apply to upstream-bound fish in midriver between and at least 3 m from the transducers. In the mixture model, ages 3 and 4 are pooled, as are ages 6 and 7. Means are weighted by daily DLMM estimates.

FIGURES

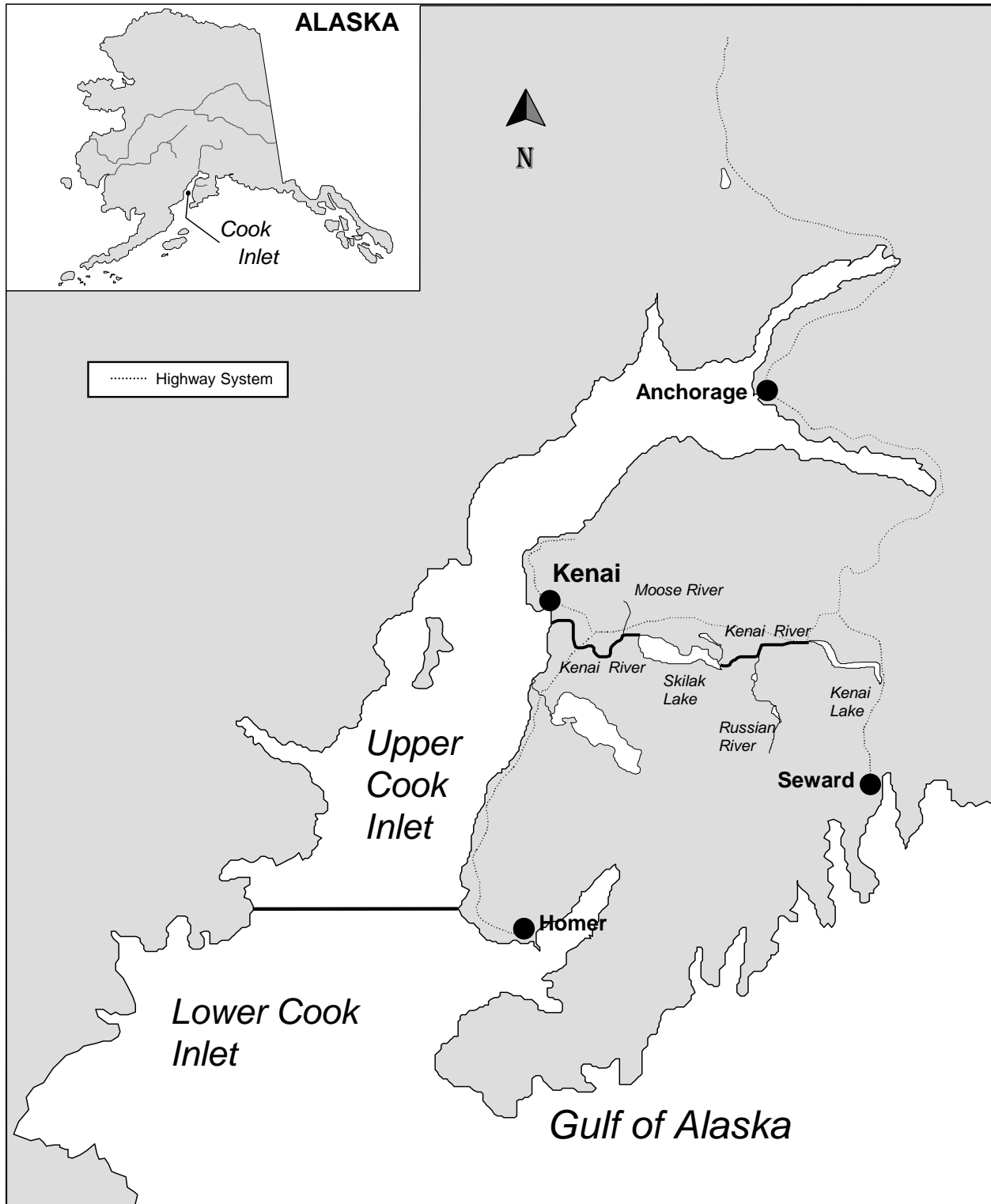


Figure 1.—Cook Inlet showing location of Kenai River.

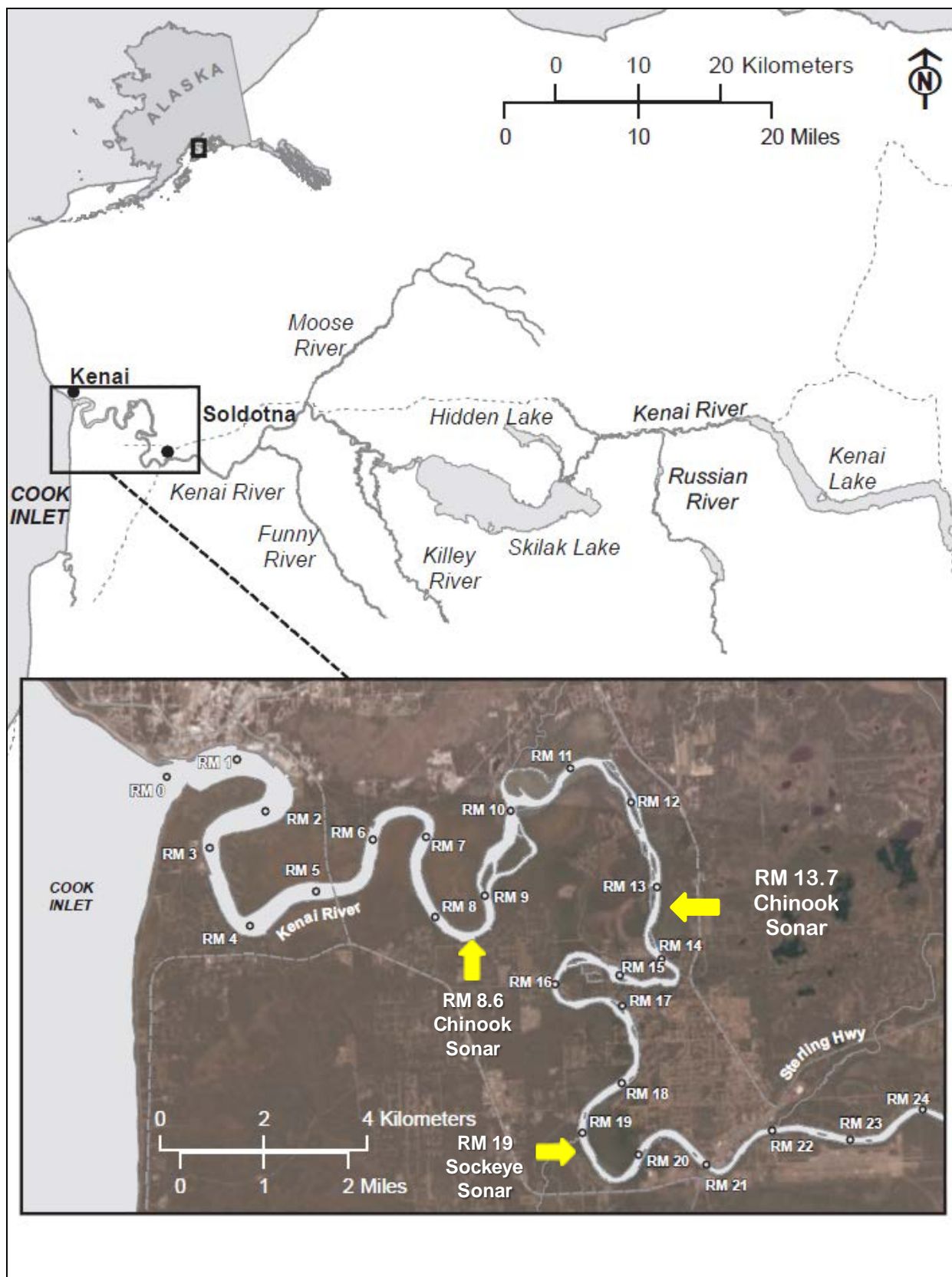


Figure 2.—Kenai River sonar site locations, 2013; this report documents findings from the RM 8.6 site.

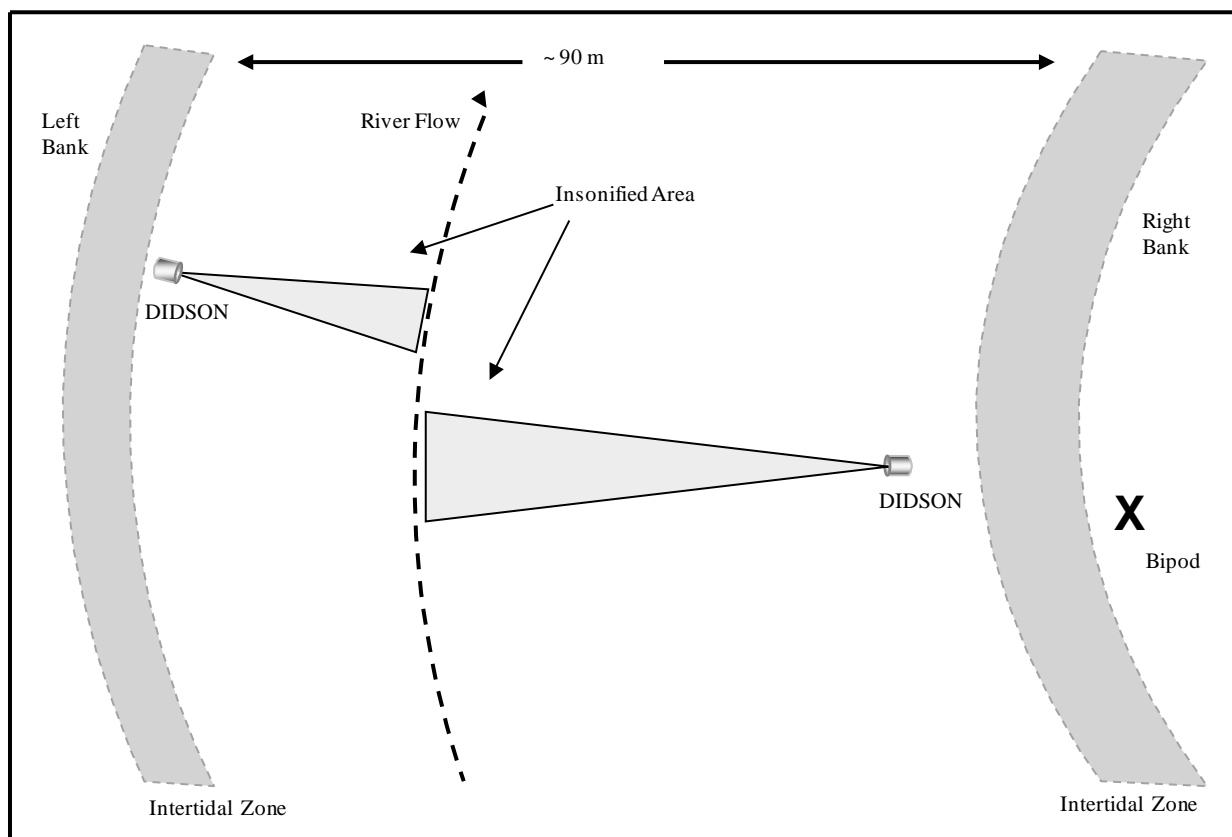
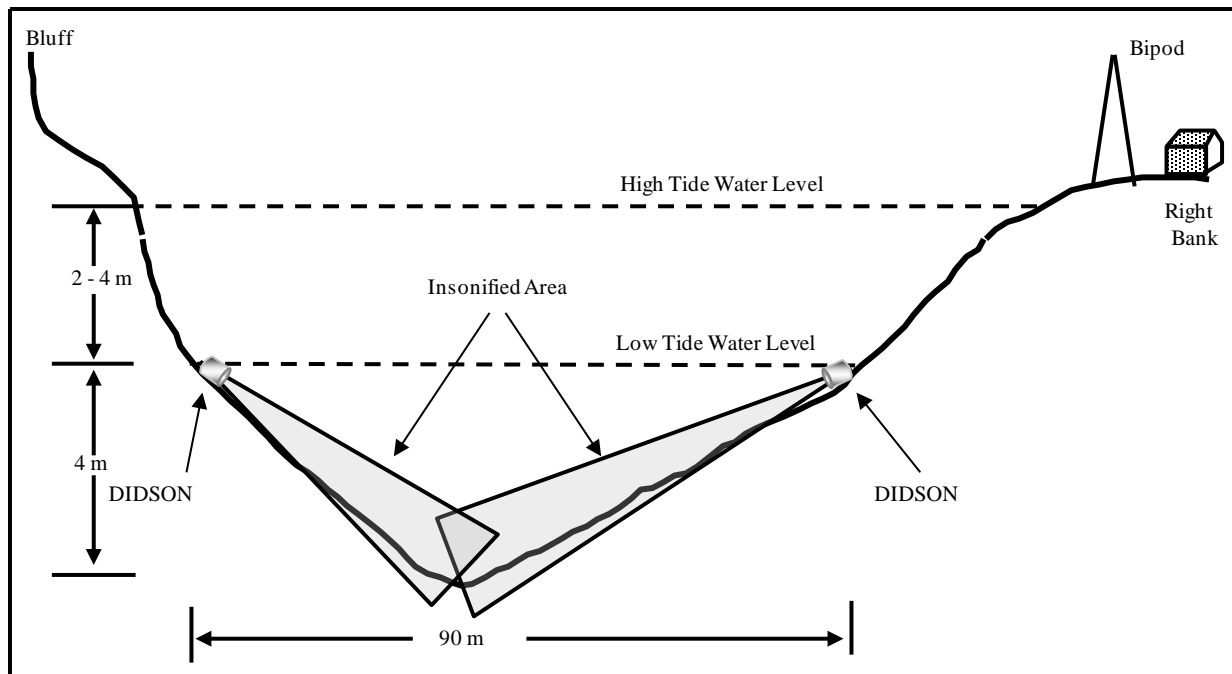


Figure 3.—Cross-sectional (top) and aerial (bottom) diagrams of sonar site illustrating insonified portions of RM 8.6 of the Kenai River, 2013.

Note: Distance from bipod to thalweg (shown as dashed line depicting lowest course of the river) is approximately 88 m.



Figure 4.—A DIDSON-LR with a high-resolution lens is mounted on a steel tripod (photo A, top) and fitted with a custom fabric enclosure (photo B, middle), which protects against silt buildup in front of the lens (photo C, bottom).

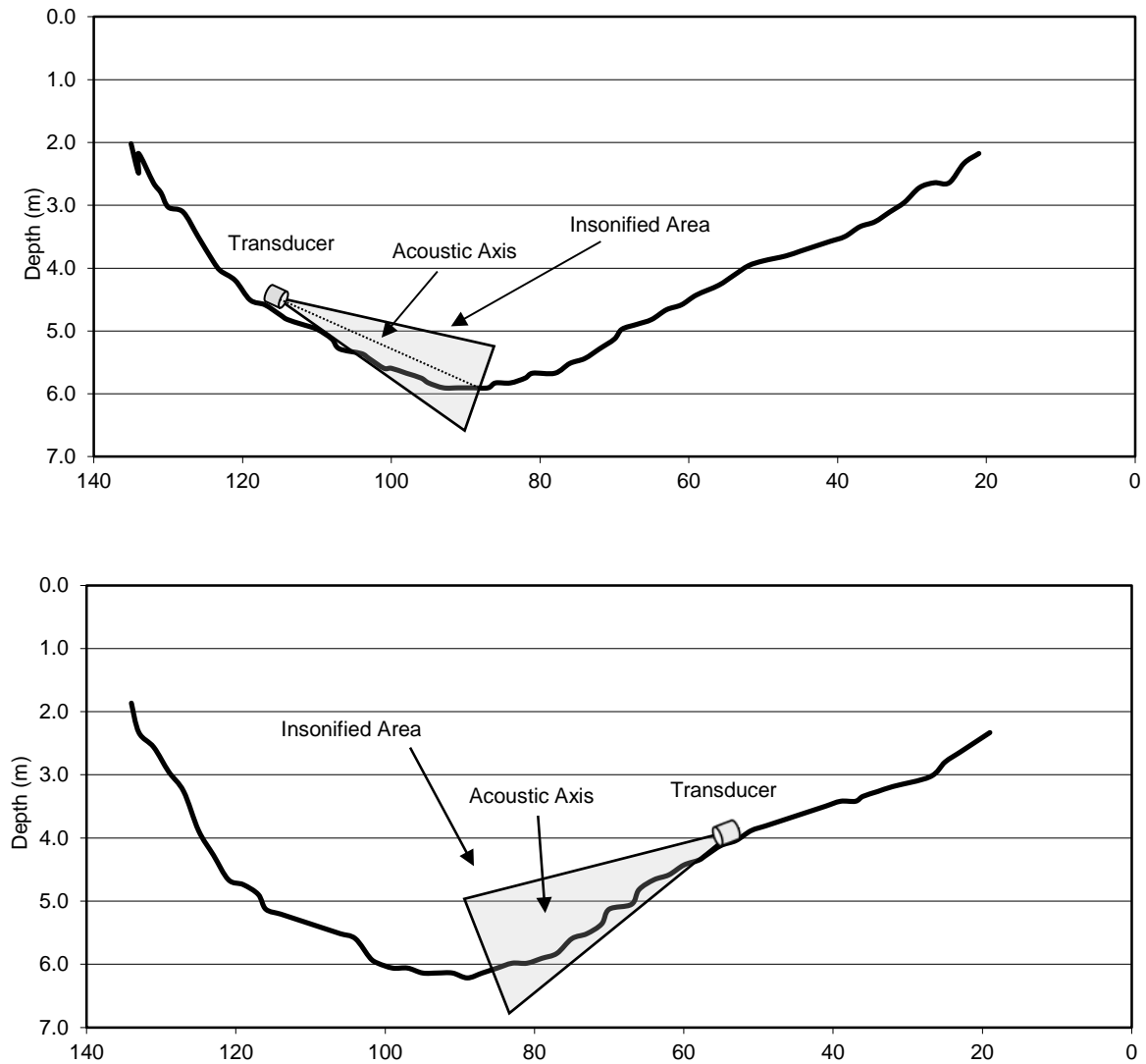


Figure 5.—Bottom profiles for the left-bank transducer (top) and right-bank transducer (bottom) at the RM 8.6 Kenai River Chinook salmon sonar site with approximate transducer placement and sonar beam coverage for 16 May 2013.

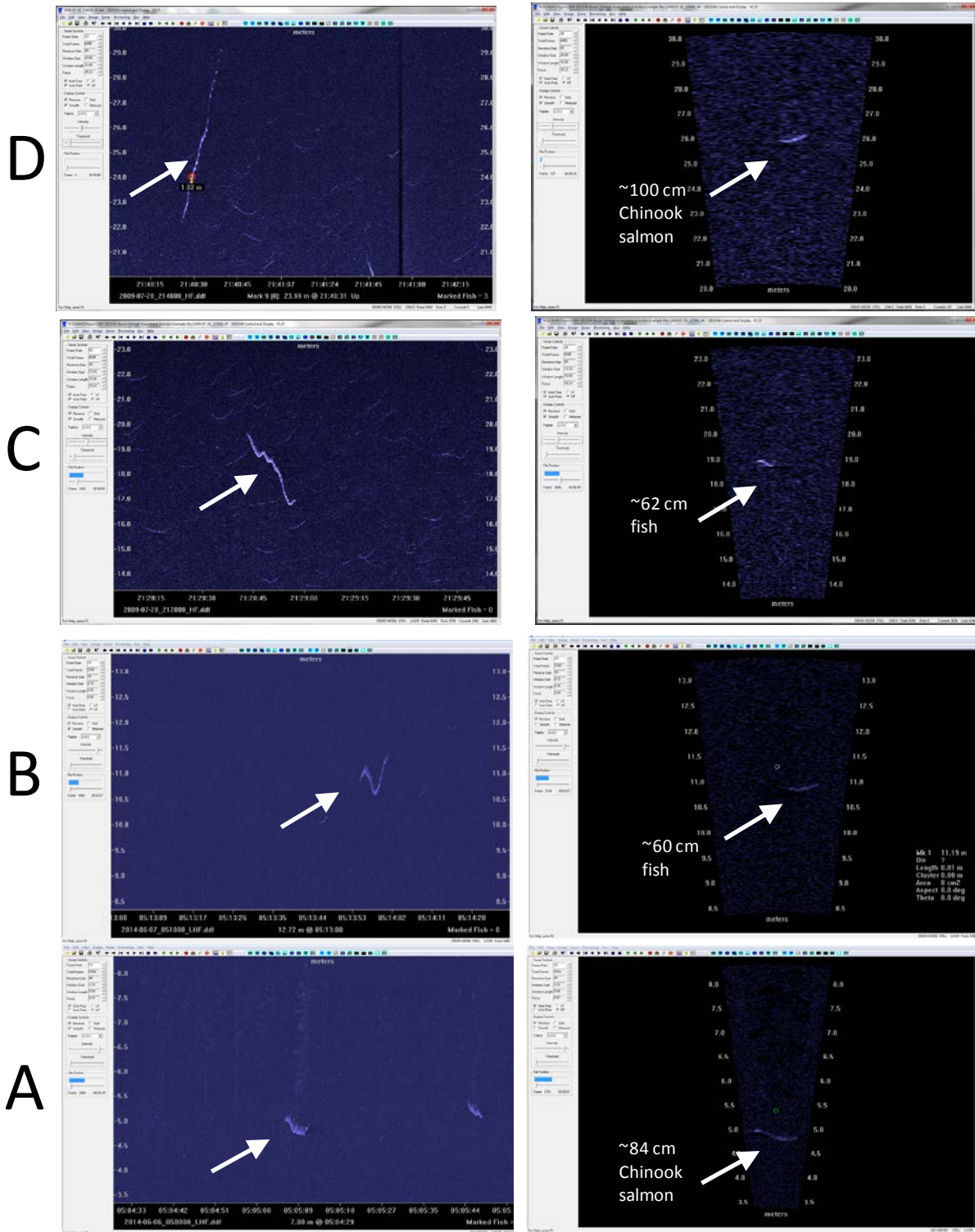
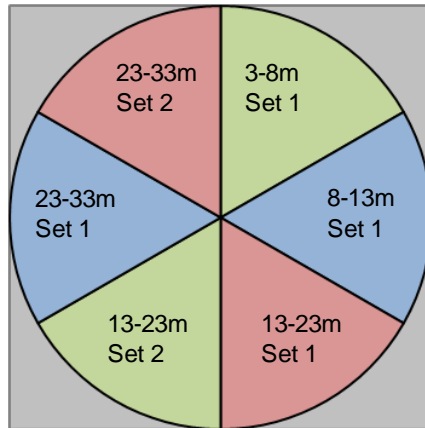


Figure 6.—Example fish traces with their measured sizes are shown on DIDSON echogram (at left) and video (at right) displays for each of the 4 range strata: 3.3–8.3 m (panel A), 8.3–13.3 m (panel B), 13.3–23.3 m (panel C), and 23.3–33.3 m (panel D).

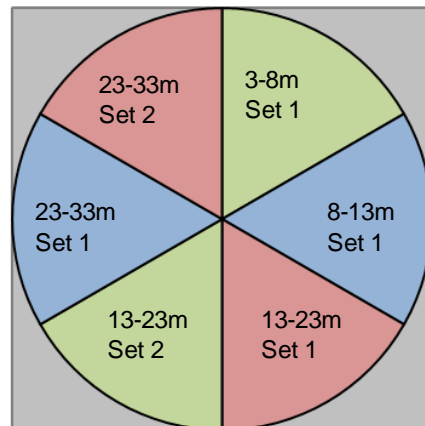
Note: The echograms display approximately 800 frames, whereas the video displays the single frame on which the measurement was taken.

Right Bank sample scheme



- xx:00-xx:10, RB 3.3-8.3m
- xx:10-xx:20, RB 8.3-13.3m
- xx:20-xx:30, RB 13.3-23.3m
- xx:30-xx:40, RB 13.3-23.3m
- xx:40-xx:50, RB 23.3-33.3m
- xx:50-xx:60, RB 23.3-33.3m

Left Bank sample scheme



- xx:00-xx:10, LB 3.3-8.3m
- xx:10-xx:20, LB 8.3-13.3m
- xx:20-xx:30, LB 13.3-23.3m
- xx:30-xx:40, LB 13.3-23.3m
- xx:40-xx:50, LB 23.3-33.3m
- xx:50-xx:60, LB 23.3-33.3m

Figure 7.—Right-bank (top) and left-bank (bottom) range strata sampling schedules for 2013 at the RM 8.6 sonar site.

Note: Time is presented in hours and minutes (hh:mm) format.

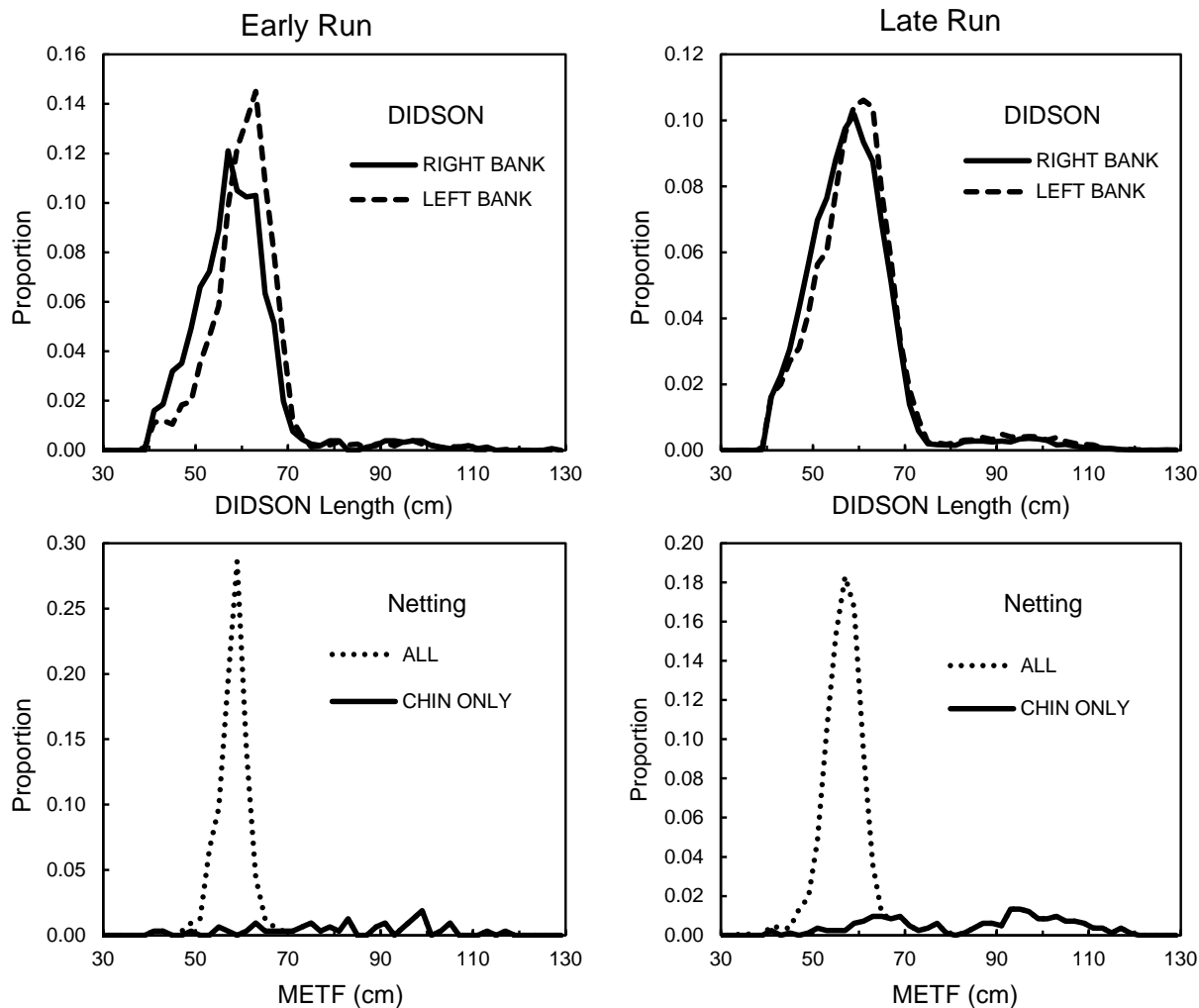


Figure 8.—Frequency distributions of fish length as measured by DIDSON (top, by bank) and lengths from mid eye to tail fork (METF) from an onsite netting project (bottom, all species vs. Chinook salmon only), Kenai River RM 8.6, early and late runs, 2013.

Note: Data were not filtered by direction of travel.

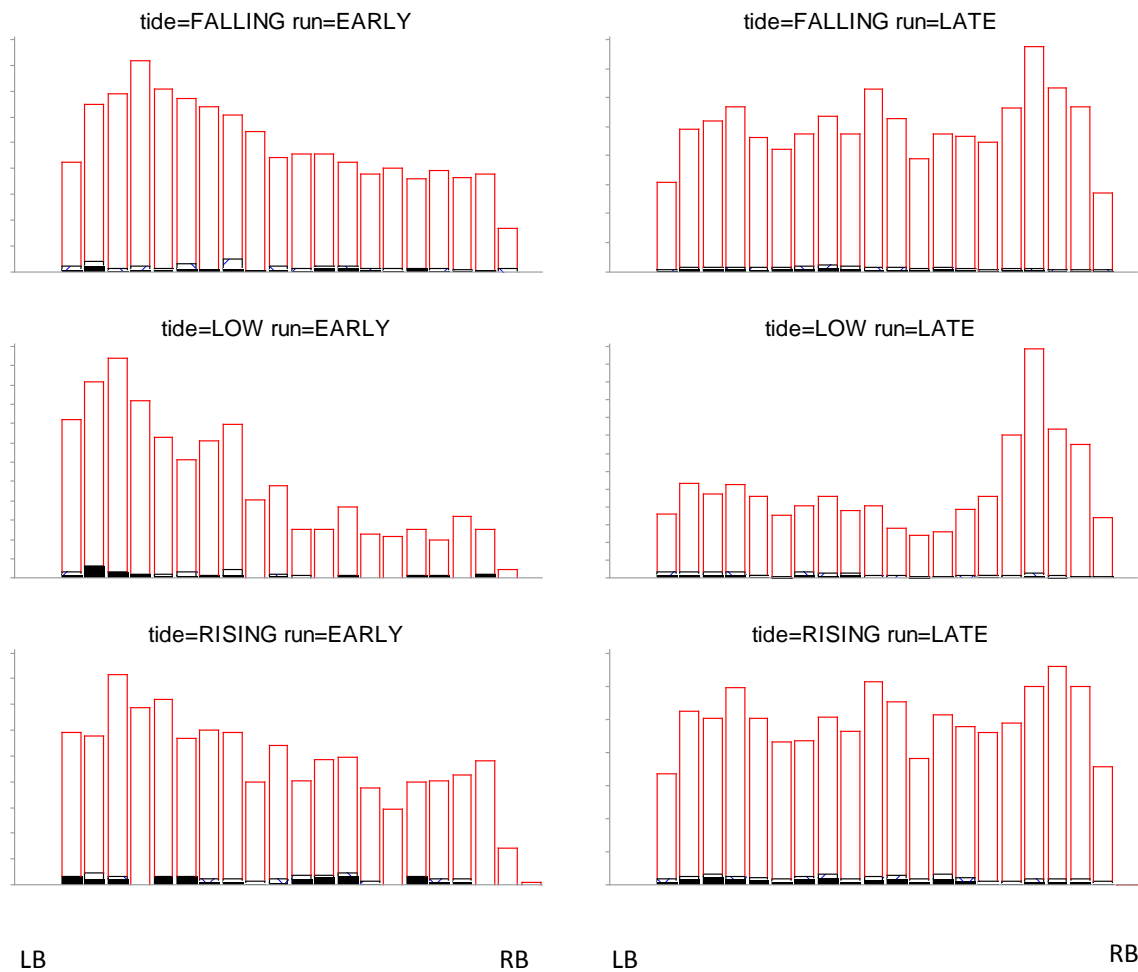


Figure 9.—Relative frequency distributions of horizontal (cross-river) position of upstream-bound fish by tide stage and DIDSON length class (black solid: ≥ 90 cm; blue hatched: 75–90 cm; red open: < 75 cm), Kenai River RM 8.6, early and late runs, 2013.

Note: Vertical axis shows percent relative frequency (all columns sum to 1 for each graph) by run and tide stage. Approximately 60 meters separates the left-bank (LB) and right-bank (RB) transducers.

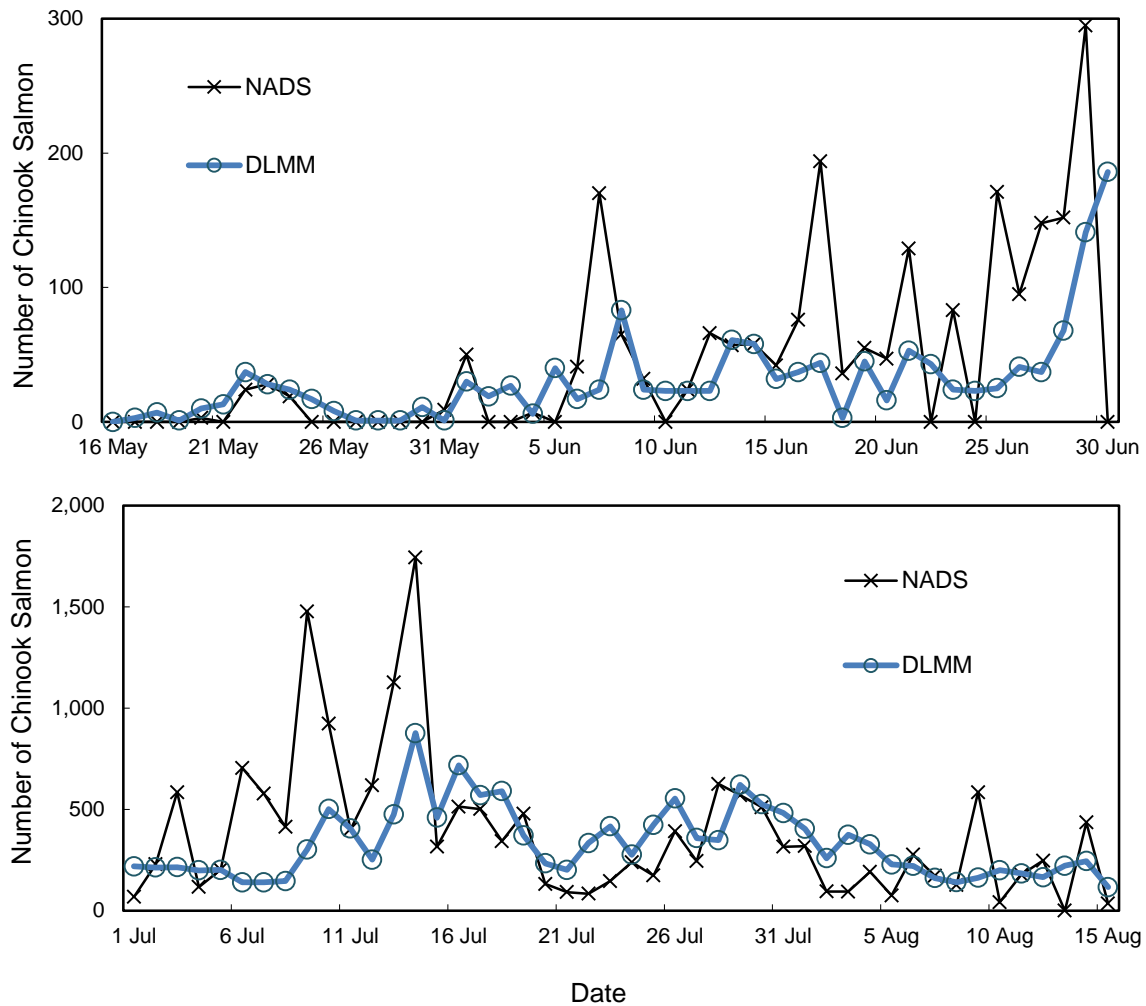


Figure 10.—Estimated upstream-bound fish passage based on net-apportioned DIDSON (NADS) and DIDSON-length mixture model (DLMM), for early- (top) and late-run (bottom) Kenai River Chinook salmon at RM 8.6, 2013.

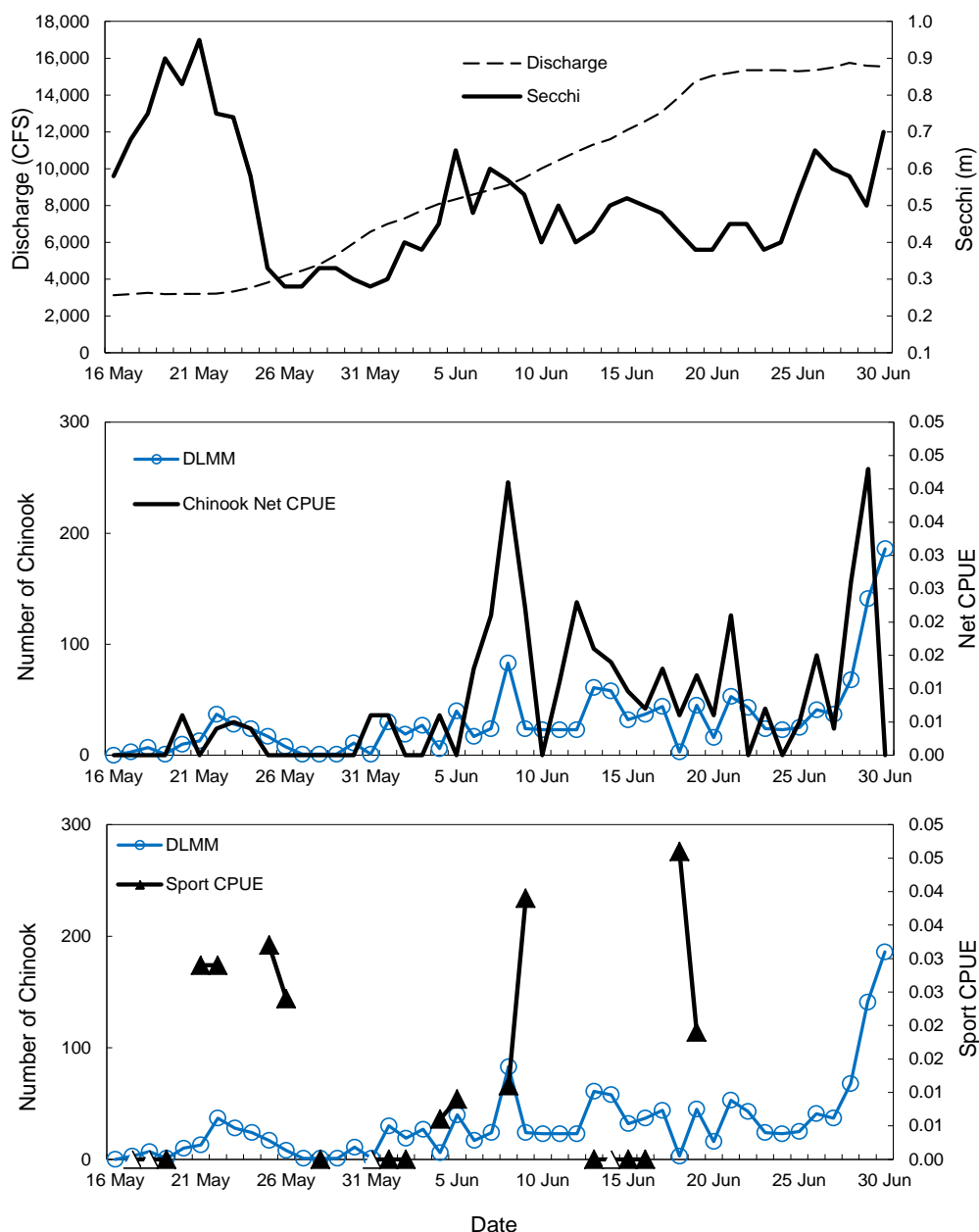


Figure 11.—Daily discharge rates collected at the Soldotna Bridge and Secchi disk readings taken from the RM 8.6 sonar site (top), DIDSON-length mixture model (DLMM) estimates of Chinook salmon passage and inriver gillnet Chinook salmon CPUE (middle) at RM 8.6, and DLMM estimates compared to Chinook salmon sport fishery CPUE (bottom), Kenai River, early run 2013.

Note: River discharge taken from USGS⁵. Net CPUE and sport fish CPUE taken from Perschbacher (2015). Open triangles represent days on which only unguided anglers were allowed to fish. The sport fishery closed after 19 June.

⁵ USGS Water resource data, Alaska, water year 2013. Website Daily Streamflow for Alaska, Soldotna gauging station, site #15266300, accessed June 23, 2015. <http://water.usgs.gov/ak/nwis/discharge>.

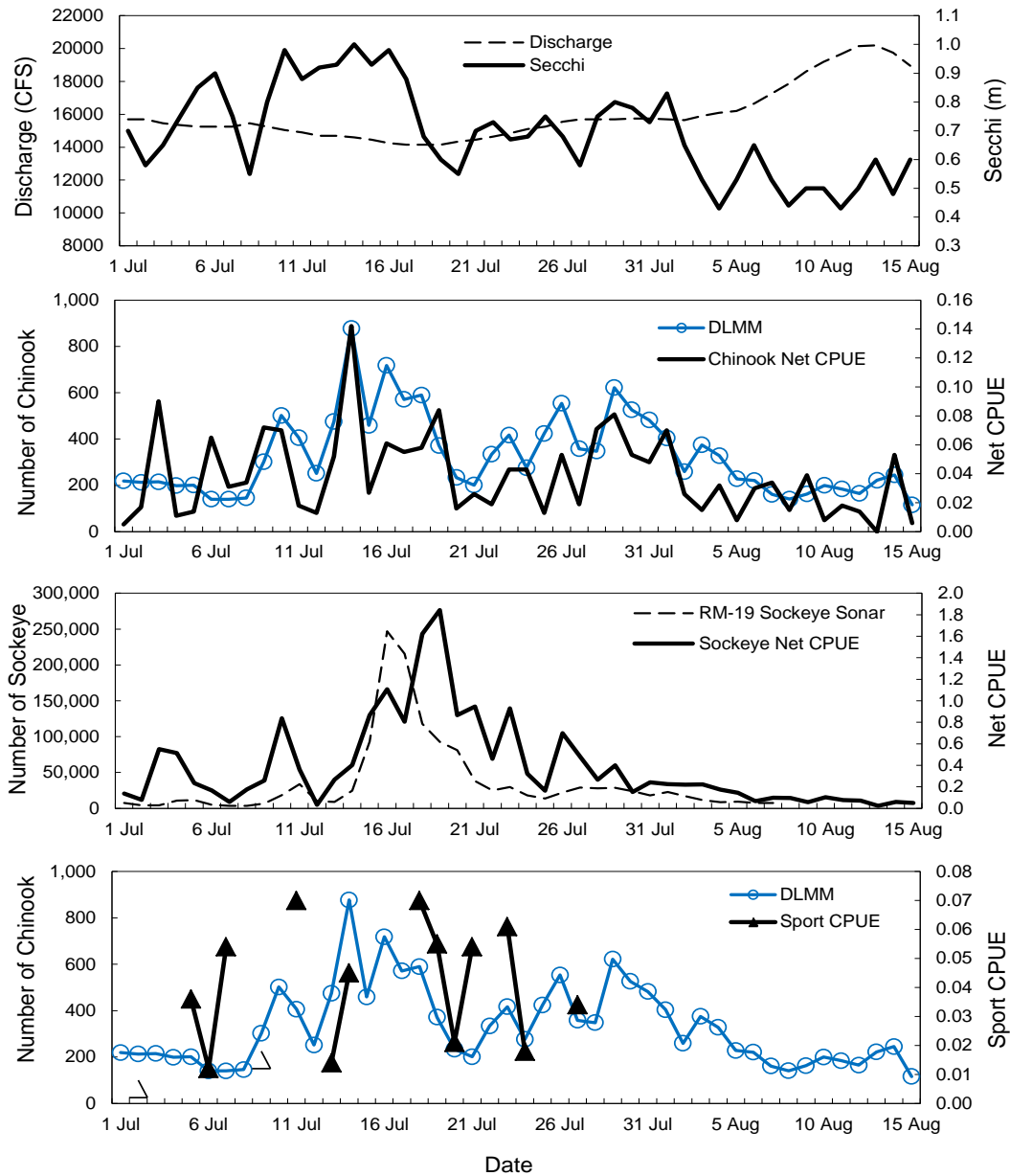


Figure 12.—Daily discharge rates collected at the Soldotna Bridge and Secchi disk readings taken at the RM 8.6 sonar site (top), DIDSON-length mixture model (DLMM) estimates of Chinook salmon passage and inriver gillnet Chinook salmon CPUE (top middle) at RM 8.6, RM 19 sockeye salmon sonar passage and inriver gillnet sockeye salmon CPUE (bottom middle), and DLMM estimates compared to Chinook salmon sport fishery CPUE (bottom), Kenai River, late run, 2013.

Note: River discharge taken from USGS⁶. Net CPUE and sport fish CPUE taken from Perschbacher (2015). Open triangles represent days on which only unguided anglers were allowed to fish. Sockeye salmon RM 19 sonar is from Glick (2015). The sport fishery closed after 27 July.

⁶ USGS Water resource data, Alaska, water year 2013. Website Daily Streamflow for Alaska, Soldotna gauging station, site #15266300, accessed June 23, 2015. <http://water.usgs.gov/ak/nwis/discharge>.

**APPENDIX A: DIDSON CONFIGURATION FOR KENAI
RIVER CHINOOK SONAR STUDY, 2013**

Selection of the appropriate DIDSON hardware configuration and operating parameters is primarily determined by the range and resolution needs of a specific application. Because resolution generally decreases as the insonified range increases, the need to balance and optimize these parameters determined the configuration used at the Kenai River RM 8.6 site.

Frequency

DIDSON sonars operate at 2 frequencies: a higher frequency that produces higher-resolution images and a lower frequency that can detect targets at farther ranges but at a reduced image resolution. Two DIDSON models are currently available based on different operating frequencies (Appendix A2). The short-range or standard model (DIDSON-S) operates at 1.8 MHz to approximately 15 m and 1.1 MHz to approximately 30 m and produces higher-resolution images than the long-range model. The long-range model (DIDSON-LR) operates at 1.2 MHz to approximately 30 m and 0.7 MHz to ranges exceeding 100 m, but produces images with approximately half the resolution of the DIDSON-S (see explanation below). A long-range model (DIDSON-LR) was used in this study to insonify the required range and was operated in high-frequency mode (1.2 MHz) to achieve maximum image resolution.

Beam Dimensions and Lens Selection

The DIDSON-LR used in this study was fitted with a high-resolution lens to further enhance the image resolution of the DIDSON-LR system (DIDSON-LR+HRL). The high-resolution lens has a larger aperture that increases the image resolution by approximately a factor of 2 over the standard lens by reducing the width of the individual beams and spreading them across a narrower field of view (Appendices A2 and A3). Overall nominal beam dimensions for a DIDSON-LR with a standard lens are approximately 29° in the horizontal axis and 14° in the vertical axis. Operating at 1.2 MHz, the 29° horizontal axis is a radial array of 48 beams that are nominally 0.54° wide and spaced across the array at approximately 0.60° intervals. With the addition of the high-resolution lens, the overall nominal beam dimensions of the DIDSON-LR are reduced to approximately 15° in the horizontal axis and 3° in the vertical axis, and the 48 individual beams are reduced to approximately 0.3° wide and spaced across the array at approximately 0.3° intervals. The combined concentration of horizontal and vertical beam widths also increases the returned signal from a given target by 10 decibels (dB), which increases the range capability of the DIDSON-LR from 25 m to at least 30 m (Appendix A2). After adding the high-resolution lens, the DIDSON-LR has equivalent resolution and twice the range capabilities as the DIDSON-S. However, the reduction in beam dimensions could potentially reduce detection capabilities, particularly at very close range (e.g., at ranges less than 5 m).

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Resolution

The resolution of a DIDSON image is defined in terms of downrange and cross-range resolution where cross-range resolution refers to the width and down-range resolution refers to the height of the individual pixels that make up the DIDSON image (Appendix A4). Each image pixel in a DIDSON frame has (x, y) rectangular coordinates that are mapped back to a beam and sample number defined by polar coordinates. The pixel height defines the downrange resolution and the pixel width defines the cross-range resolution of the image. Appendix A4 shows that image pixels are sometimes broken down into smaller screen pixels (e.g., pixels immediately to the right of the enlarged pixels), which are an artifact of conversions between rectangular and polar coordinates.

“Window length” is the range interval sampled by the sonar, and it controls the down-range resolution of the DIDSON image. Because the DIDSON image is composed of 512 samples (pixels) in range, images with shorter window lengths are better resolved (i.e., down-range resolution = window length/512). Window length can be set to 2.5, 5.0, 10.0, or 20.0 m for the DIDSON-LR+HRL at 1.2 MHz. Shorter window lengths have higher resolution but require more individual strata to cover the desired range. However, dividing the total range covered into too many discrete strata increases the data-processing time. For this study, a window length of 5 m was used to minimize the bias associated with close-range targets for the first 2 range strata. When sampling at close range (less than about 8 m with a long range lens), a shorter range window (i.e., 5 m) for the first range stratum minimizes the effect of poor focal resolution at close range (Bill Hanot, Sound Metrics Corporation, personal communication). A window length of 10 m was used for each of the 2 subsequent range strata, a compromise that allowed a relatively high resolution while allowing a reasonable distance to be covered by each stratum. The downrange resolution (or pixel height) for a 5 m range window is 1 cm (500 cm/512), and for a 10 m window length is 2 cm (1,000 cm/512).

The cross-range resolution is primarily determined by the individual beam spacing and beam width, both of which are approximately 0.3° for the DIDSON LR+HRL at 1.2 MHz (Appendix A2). Targets at closer range are better resolved because the individual beam widths and corresponding image pixels increase with range following the formula below:

$$X = 2R \tan\left(\frac{\theta}{2}\right) \quad (A1)$$

where

- X = width of the individual beam or “image pixel” in meters,
- R = range of interest in meters, and
- θ = individual beam angle in degrees (approximately 0.3°).

Other Settings

The transmit power of the DIDSON sonar is fixed but the receiver gain is user-configurable. The maximum receiver gain (−40 dB) was used during all data collection. The autofocus feature was enabled so that the sonar automatically set the lens focus to the midrange of the selected display window (e.g., for a window length of 15 m that started at 10 m, the focus range would be $15 \text{ m} + [10 \text{ m}/2] = 20 \text{ m}$).

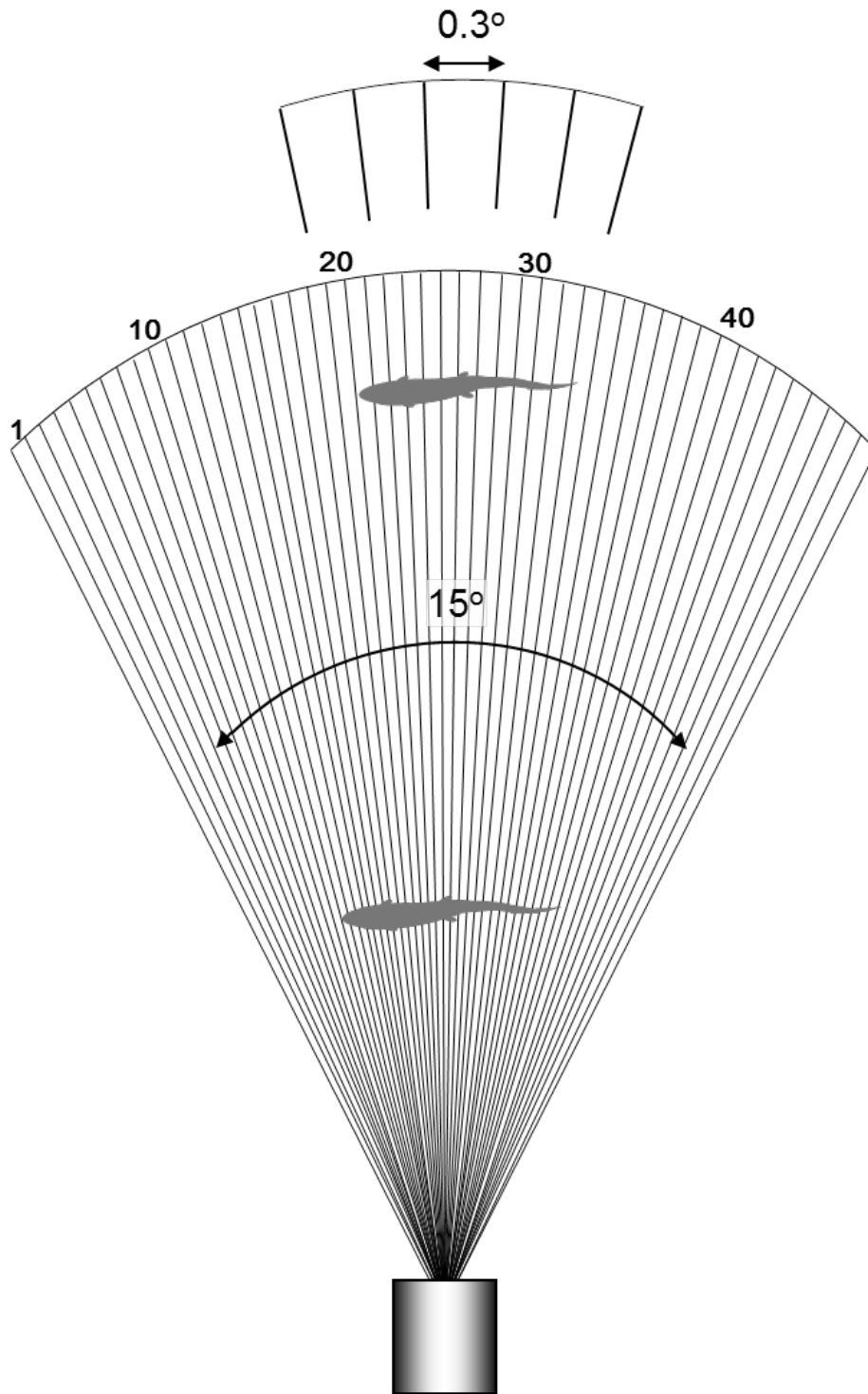
Appendix A2.–Summary of manufacturer specifications for maximum range, individual beam dimensions, and spacing for a DIDSON-S and a DIDSON-LR with (HRL) and without the addition of a high-resolution lens (specifications from Sound Metrics Corporation).

System	Maximum range (m) ^a	Horizontal beam width	Vertical beam width	Number of beams	Individual beam width ^{b,c}	Individual beam spacing ^{b,c}
DIDSON-S (1.8 MHz)	15	29°	14°	96	0.30°	0.30°
DIDSON-S (1.1 MHz)	30	29°	14°	48	0.40°	0.60°
DIDSON-S (1.8 MHz) +HRL	20	15°	3°	96	0.17°	0.15°
DIDSON-S (1.1 MHz) +HRL	40	15°	3°	48	0.22°	0.30°
DIDSON-LR (1.2 MHz)	25	29°	14°	48	0.40°	0.30°
DIDSON-LR (0.7 MHz)	80	29°	14°	48	0.60°	0.60°
DIDSON-LR (1.2 MHz) +HRL	30	15°	3°	48	0.27°	0.30°
DIDSON-LR (0.7 MHz) +HRL	100	15°	3°	48	0.33°	0.60°

^a Actual range will vary depending on site and water characteristics.

^b Beam width values are for 2-way transmission at the –3 dB points.

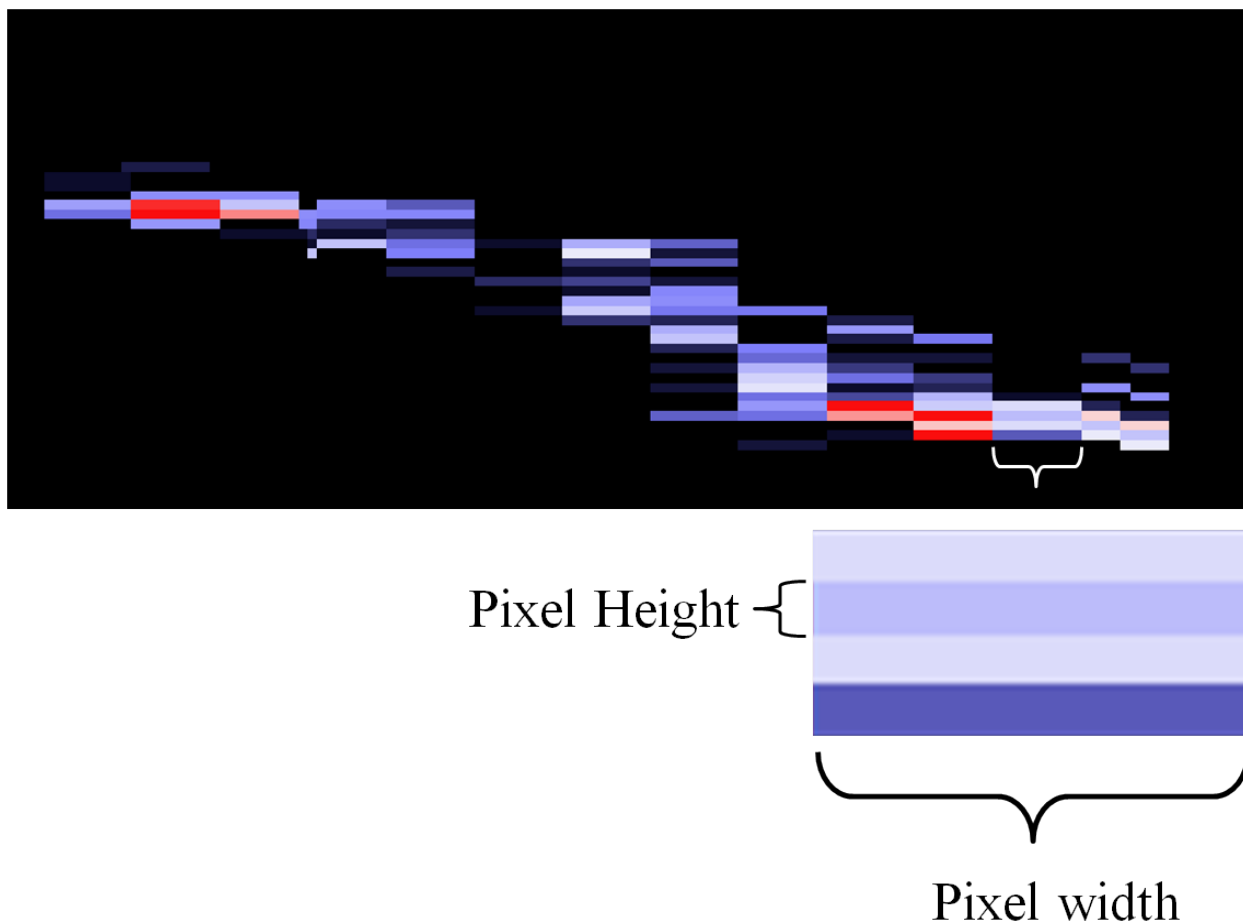
^c Values for beam spacing and beam width are approximate. Beam widths are slightly wider near the edges of the beam and the beam spacing is slightly narrower. Conversely, beams are slightly narrower near the center of the beam, and the beam spacing is slightly wider (e.g., the center beam spacing is closer to 0.34°, and the beam width is 0.27° for a DIDSON-S at 1.8 MHz (Bill Hanot, Sound Metrics Corporation, personal communication). Nonlinear corrections are applied by the manufacturer in software to correct for these effects in the standard (but not the high-resolution) lens.



Appendix A3.—Diagram showing the horizontal plane of a DIDSON-LR sonar with a high-resolution lens (DIDSON-LR+HRL).

Source: Adapted from Burwen et al. (2007).

Note: The overall horizontal beam width of 15° is composed of 48 sub-beams with approximately 0.3° beam widths. Fish at close range are better resolved than fish at far range because the beam widths grow wider with range.



Appendix A4.—An enlargement of a tethered Chinook salmon showing the individual pixels that compose the image.

Source: Adapted from Burwen et al. (2010).

Note: Each image pixel in a DIDSON frame has (x, y) rectangular coordinates that are mapped back to a beam and sample number defined by polar coordinates range.

Parameter setup prior to beginning measurements

- Step 1. Set the number of frames displayed (i.e., when right-clicking on a fish in echogram mode to display in movie mode) from the default of plus-minus one second to plus-minus any number of frames:
- 1) Select **<image><playback><set endpoints>**.
 - 2) [✓] Loop on still for +/- N frames.
 - 3) Enter the number of frames (suggestion: 20–30).
- Step 2. Select **<Processing><Echogram><Use Cluster Data>** to use ALL the beams when creating the echogram (we generally do). Use fewer beams by unchecking this option and selecting the number of beams.
- Step 3. Set up **processing parameters** (last Icon on right) for **File Creation** as follows:
- 1) Auto Countfile Name
 - 2) Binary CountFile (.dat)
 - 3) New Countfile on Open
 - 4) Echogram File (.ech)
- Step 4. Echogram counts can be reloaded to finish or review at a later time if the Echogram file has been checked as follows:
- 1) Select **<File><Open>** then **Files of type .ech** from drop-down menu.
 - 2) Open desired file.
 - 3) The Echogram file should reload showing previous measurements.
- Or this option will work as long as the .dat file has been saved (as shown above):
- 1) Open the file and bring up the echogram (follow instructions below).
 - 2) Select **<Processing><Echogram><Import Echogram Counts>**.
 - 3) Select the **.dat** file with saved counts. The file should reload, showing previous measurements (the filename for the .dat file will begin with **FC_**).
- Step 5. Make sure **<Image><Configure><Auto Threshold/Intensity>** is **UNCHECKED**. This will keep the threshold and intensity settings from changing when switching between Echogram and Movie mode.
- Step 6. Uncheck the “Display Raw Data” toolbar icon (first button on left in Combined toolbar). (If you are in Movie mode and it is displaying the raw image data, it is because “Display Raw Data” is enabled by default).

Instructions for manual echogram-based length measurements

***Note that these settings may already be active because some of them have “memory” and are saved until changed.**

- 1) Select **<BS>** (background subtraction) from toolbar or under **<Processing><Background><Background Subtraction>**.
- 2) Select **<Processing><Background><Fixed Background>**.
- 3) Select the threshold and intensity settings for each range stratum as indicated in the table below. To adjust these settings, use slider bars under the Display Controls to the left side of the Echogram or Movie window.

	3-8m	8-13 m	13–23 m	23–33 m
Threshold	11	11	10	9
Intensity	50	50	45	40

-continued-

- 4) Select <EG> (for view echogram) from toolbar or under <Processing><Echogram><View echogram>.
- 5) <left click> on the echogram near or on the fish trace of interest to “mark it.” A white circle should be visible.
- 6) <right click> INSIDE the white circle to switch to Movie mode (Movie mode will play the 16 frames encompassing this circle continuously).
- 7) Press <space bar> to pause the movie.
- 8) Step through the movie frames using the right or left arrows until finding a frame that displays the entire length of the fish well (see section below for selecting optimal images).
- 9) <right mouse click drag> will magnify the area in the rectangle.
- 10) <left click> on the FISH SNOUT and continue to <left click> along the body to create a “segmented measurement.” *The segments should follow the midline of the body of the fish* ending with the tail. Try not to use more than 3 or 4 segments to define the fish (see section below for selecting optimal images).
- 11) <double left click> or select <f> key to add measurement to file.
- 12) <right click> to unzoom.
- 13) <right click> to return to the echogram.

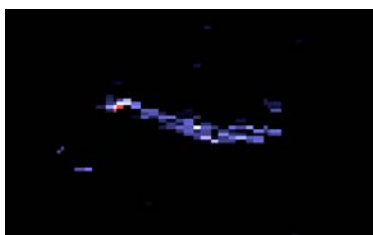
Hot keys

- 1) <e> to “save” all echogram measurements to file
- 2) <f> to “fish it” (to accept the measurement and display it on the echogram)
- 3) <u> to “undo” the last segment
- 4) <d> to “delete” the all segments
- 5) <space bar> to pause in Movie mode (if this doesn’t work, click in the black area of the display)
- 6) <right arrow> forward direction when selecting play or advances frame one at a time if the pause button is on (pause button = blue square on the toolbar)
- 7) <left arrow> opposite of above
- 8) **Left Click Drag** to show movie over the selected time
- 9) **Right Click Drag** zooms the selected area

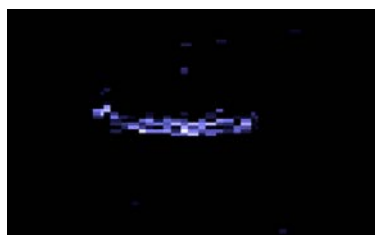
Selecting optimal images to measure

Measurements should be taken from frames where contrast between the fish image and background are high and where the fish displays its full length (e.g., panels a, d, and f in Appendix A6). In general, the best images are obtained when the fish is sinusoidal in shape, rather than linear (e.g., panel “c” in Appendix A6), because it is easier to identify the snout and tail and to assess whether the entire length of the fish is visible when there is some curvature to the fish body (e.g., Appendices A6 and A7). Images that appear distorted or truncated should not be measured. For example, under some conditions where a fish is highly reflective or near range, the image will appear “smeared” out into adjacent beams. This condition, also referred to as “arc-ing,” most often occurs when the target is both linear and perpendicular relative to the sonar beams as in shown in Appendix A8.

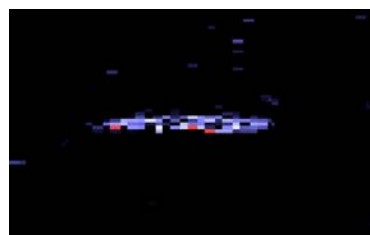
Appendix A7 demonstrates the process of measuring a fish using the manual measuring tool. The user pauses the DIDSON movie (top), zooms in on the fish of interest (middle), and measures the fish length with a segmented line created by mouse clicks along the center axis of the fish (bottom). The user selects the leading pixel edge of the snout to start the measurement (yellow start pixel extends beyond snout) and clicks just before the trailing edge of the pixel(s) defining the tail such that the “yellow measurement line” is flush with the trailing pixel edge.



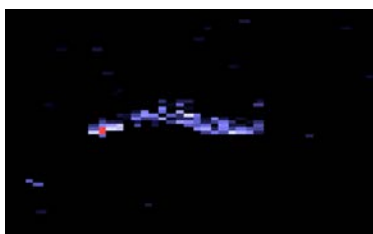
(a) 99.4 cm



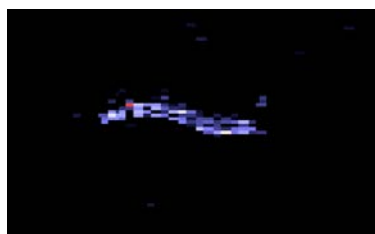
(b) 87.6 cm



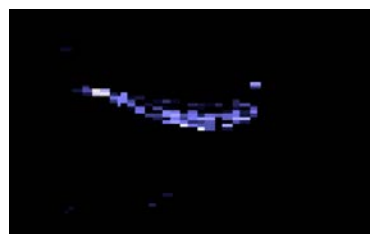
(c) 89.8 cm



(d) 97.7 cm



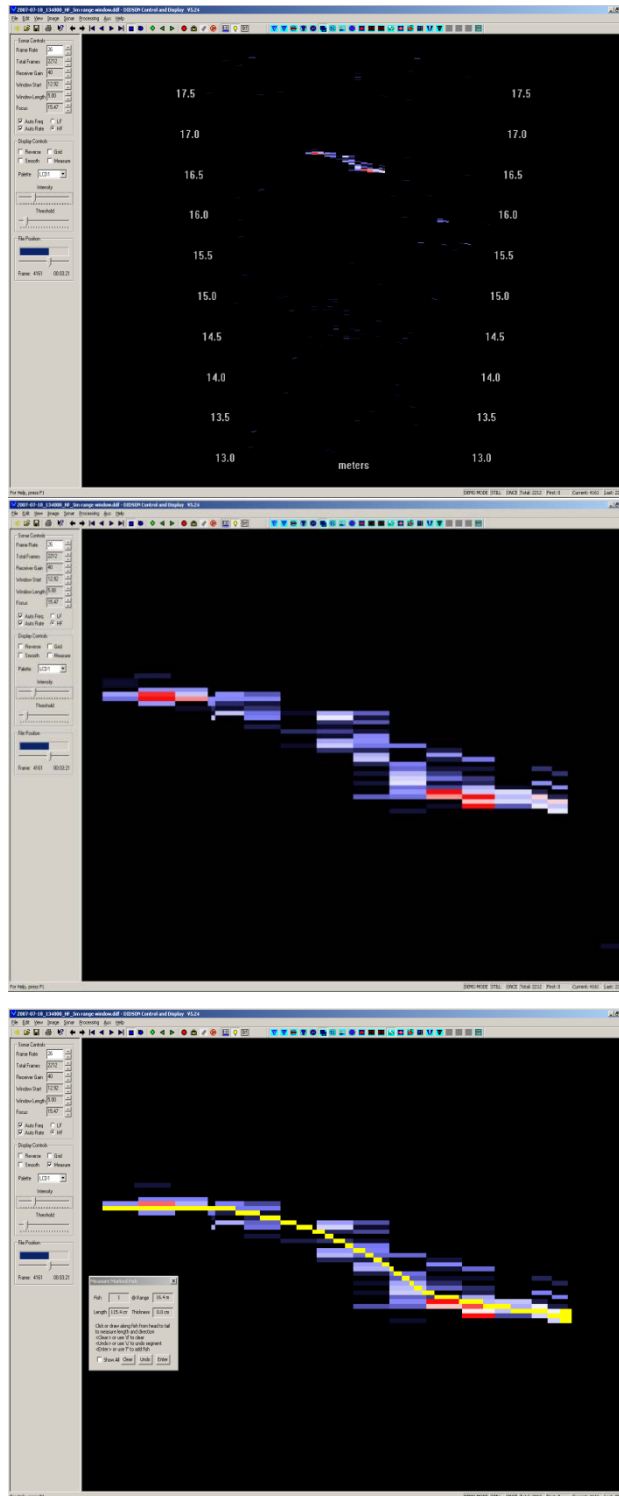
(e) 86.2 cm



(f) 98.6 cm

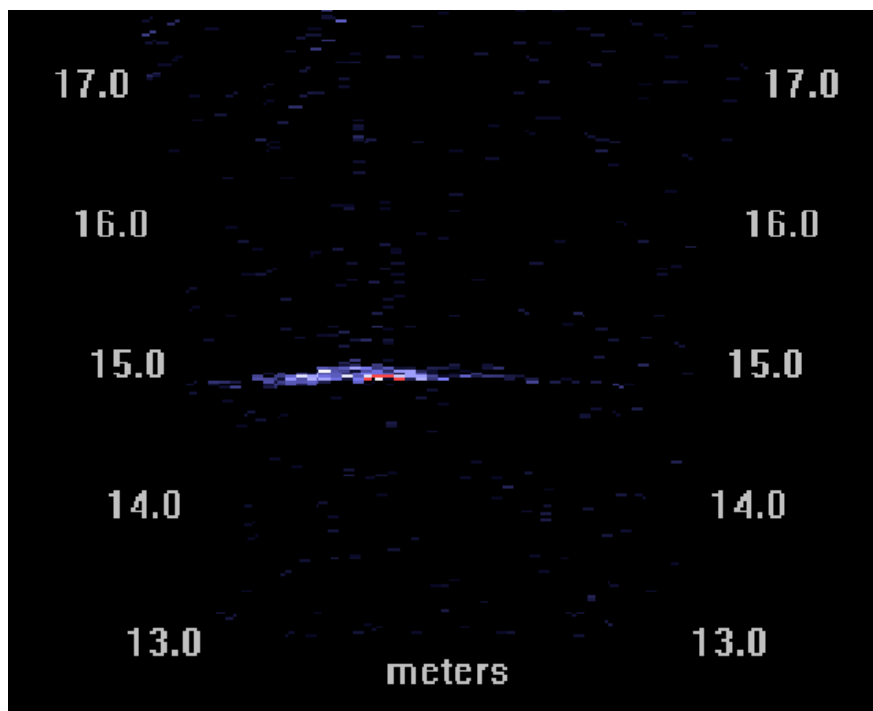
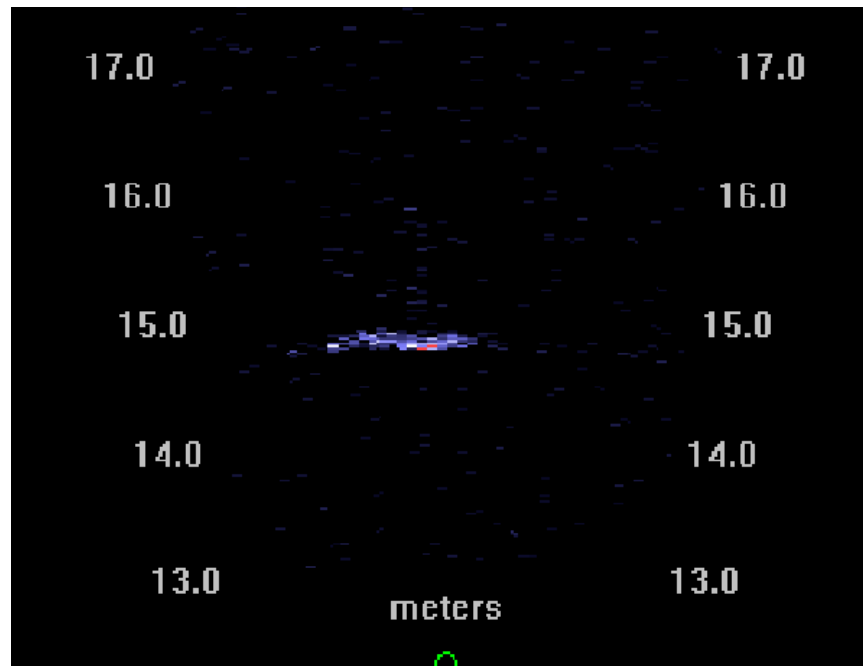
Appendix A6.—Panels a–f show the variability in length measurements from DIDSON images of a tethered Chinook salmon during 1 full tail-beat cycle.

Source: Adapted from Burwen (2010).



Appendix A7.–DIDSON images from a tethered Chinook salmon showing the original DIDSON image (top), the zoomed image (middle), and the segmented lines that result when the observer clicks along the length of the fish to mark its length (bottom).

Source: Adapted from Burwen (2010).



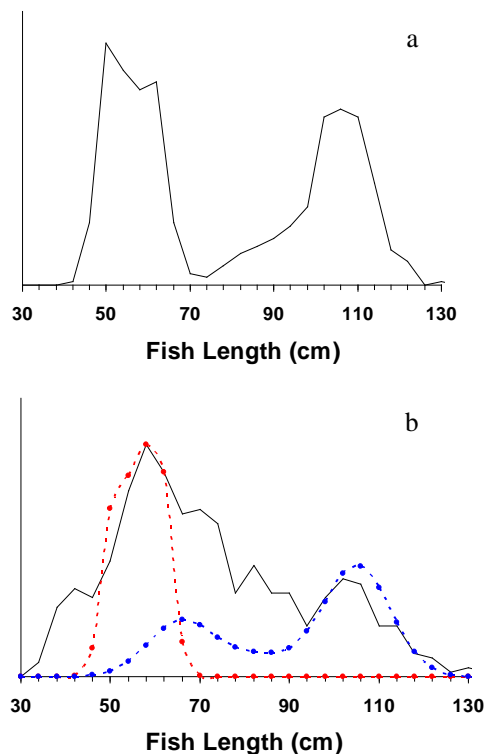
Appendix A8.—DIDSON images from a Chinook salmon showing a well-defined image of the fish swimming through the beam (top) and a “smeared” image of the same fish (bottom).

APPENDIX B: STATISTICAL MIXTURE MODEL USED TO ESTIMATE SPECIES COMPOSITION OF PASSING FISH

Appendix B1.–Mixture model description.

Mixture models are useful for extracting information from the observed frequency distribution of a carefully selected measurement. For example, if the exact length but not the species of every fish passing the sonar were known, the distribution of such measurements might resemble graph “a” in the figure below. With auxiliary information about sockeye and Chinook salmon size, the shape of such a distribution can reveal much about the relative abundance of sockeye and Chinook salmon. For instance, if sockeye salmon were known not to exceed 70 cm and small Chinook salmon were known to be rare, one could conclude that the left-hand mode of the distribution is almost all sockeye salmon and that the species composition is perhaps 50:50 sockeye salmon to Chinook salmon. Mixture model analysis is a quantitative version of this assessment in which the shape of the overall frequency distribution is modeled and “fitted” until it best approximates the data. Uncertainty is assessed by providing a range of plausible species compositions that could have resulted in the observed frequency distribution.

The mixture model analysis is sensitive to and accounts for measurement error. For example, if many Chinook salmon are small and there is error in the length measurements, the effect of the measurement error is to cause the modes of the distribution to overlap, reducing the ability to detect detail in the length distribution and reducing the precision of the estimates (e.g., graph “b” of the figure below). Under this scenario, it is more difficult to interpret the data, but a mixture model approach can provide objective estimates with realistic assessments of uncertainty.



Note: True length distributions of sockeye salmon (red dashed line) and Chinook salmon (blue dashed line) are shown along with hypothetical distributions of fish length measurements (black dashed line).

-continued-

The mixture model approach explicitly incorporates the expected variability in hydroacoustic measurements (known from tethered fish experiments), as well as current information about fish size distributions (from the onsite netting program).

The probability density function (PDF) of DIDSON length measurements w was modeled as a weighted mixture of 2 component distributions arising from sockeye salmon and Chinook salmon:

$$f(w) = \pi_S f_S(w) + \pi_C f_C(w) \quad (\text{B1})$$

where $f_S(w)$ and $f_C(w)$ are the PDFs of the sockeye salmon and Chinook salmon component distributions, and the weights π_S and π_C are the proportions of sockeye salmon and Chinook salmon in the population. See also flow chart in Appendix B2.

Individual observations of w for fish i were modeled as normal random variables whose mean is a linear function of true fish length x :

$$w_i = \beta_0 + \beta_1 x_i + \varepsilon_i \quad (\text{B2})$$

where β_0 is the intercept, β_1 is the slope, and the error ε_i is normally distributed with mean 0 and variance σ^2 .

Thus, the component distributions $f_S(w)$ and $f_C(w)$ are functions of the length distributions $f_S(x)$ and $f_C(x)$ (see Equations B3–B4) and the linear model parameters β_0 , β_1 , and σ^2 . The species proportions π_S and π_C are the parameters of interest.

Length measurements were obtained from fish captured by gillnets (Perschbacher 2014) immediately downstream of the sonar site. The netting program was designed to sample the river corridor insonified by DIDSON. Length data from the nets were paired with hydroacoustic data from the same time periods.

Sockeye and Chinook salmon return from the sea to spawn at several discrete ages. We modeled sockeye and Chinook salmon length distributions ($f_S(x)$ and $f_C(x)$, respectively) as 3-component normal age mixtures:

$$f_S(x) = \theta_{S1} f_{S1}(x) + \theta_{S2} f_{S2}(x) + \theta_{S3} f_{S3}(x) \text{ and} \quad (\text{B3})$$

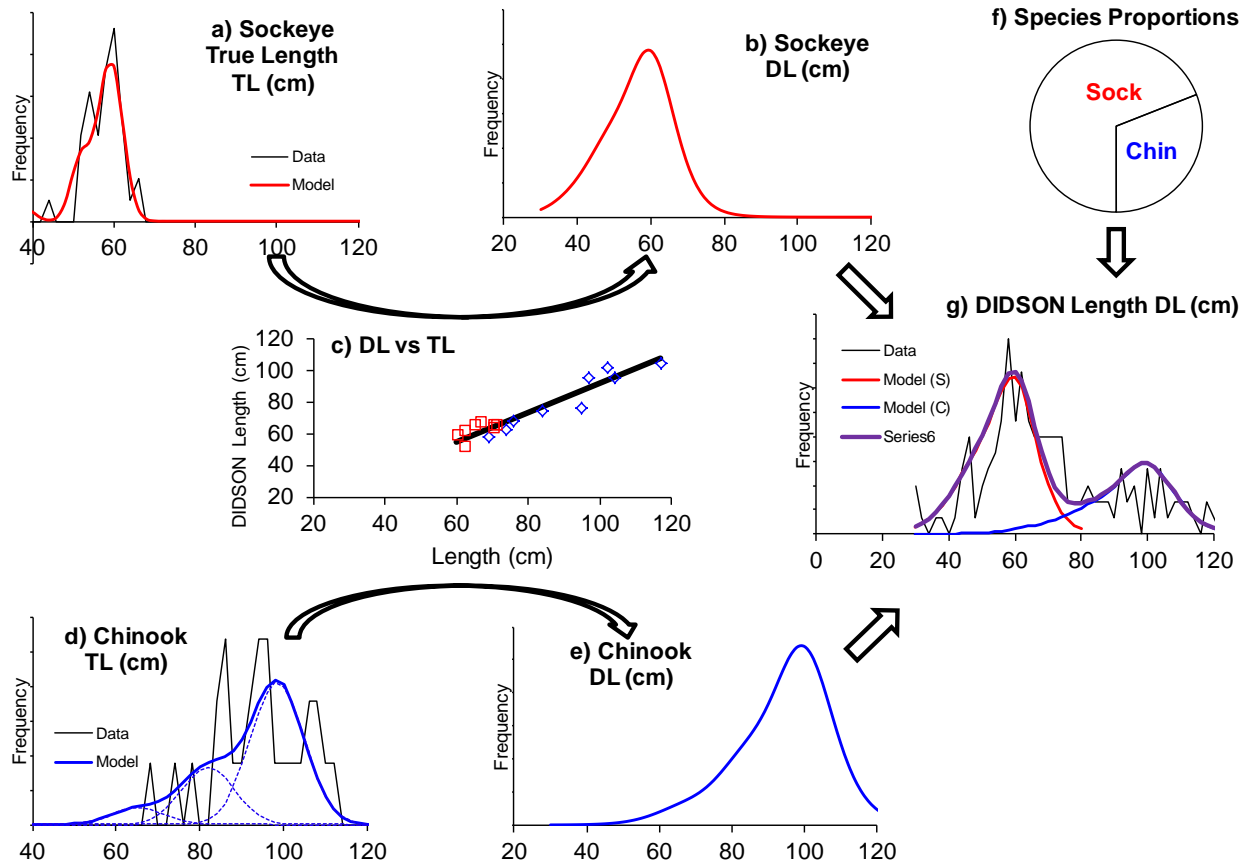
$$f_C(x) = \theta_{C1} f_{C1}(x) + \theta_{C2} f_{C2}(x) + \theta_{C3} f_{C3}(x) \quad (\text{B4})$$

where θ_{Ca} and θ_{Sa} are the proportions of sockeye and Chinook salmon belonging to age component a and the distributions

$$f_{Sa}(x) \sim N(\mu_{Sa}, \tau_{Sa}^2), \text{ and} \quad (\text{B5})$$

$$f_{Ca}(x) \sim N(\mu_{Ca}, \tau_{Ca}^2) \quad (\text{B6})$$

where μ is mean length-at-age and τ is the standard deviation. The overall design is therefore a mixture of (transformed) mixtures. That is, the observed hydroacoustic data are modeled as a 2-component mixture (sockeye salmon and Chinook salmon) of DIDSON length (w), each component of which is transformed from a 3-component normal age mixture of fish length (x).



Appendix B2.—Flow chart of a mixture model. The frequency distribution of DIDSON length (DL, panel “g”) is modeled as a weighted mixture of species-specific DL distributions (panels “b” and “e”), which in turn are the products of species-specific size distributions (panels “a” and “d”) and the relationship between DL and true fish length (panel “c”). The weights (species proportions, panel “f”) are the parameters of interest.

Bayesian statistical methods were employed to fit the mixture model to the data. Bayesian methods were chosen because they provide realistic estimates of uncertainty and the ability to incorporate diverse sources of auxiliary information. We implemented the Bayesian mixture model in WinBUGS (Bayes Using Gibbs Sampler; Gilks 1994). Bayesian methods require that prior probability distributions be formulated for all unknowns in the model (Gelman 2004). Species proportions π_S and π_C were assigned an uninformative Dirichlet(0.1,0.9) prior. Age proportions $\{\theta_{Sa}\}$ and $\{\theta_{Ca}\}$ were assigned informative Dirichlet priors based on a hierarchical analysis of historical data (Appendix B4). Likewise, informative normal priors based on historical data were used for the length-at-age means μ and standard deviations τ (Appendix B5). A linear statistical model of tethered fish data (Burwen et al. 2003) was integrated into the mixture model (Appendix B5) to provide information on regression parameters β_0 , β_1 , and σ^2 .

WinBUGS uses Markov chain Monte Carlo methods to sample from the joint posterior distribution of all unknown quantities in the model. A single Markov chain⁷ (Gelman 2004) was initiated for each daily run of the hierarchical age composition model, samples were thinned 20 to 1, and history plots were monitored to confirm convergence and mixing. The first 4,000 or more “burn-in” samples were discarded, and at least 10,000 additional samples were drawn from the posterior distribution.

The end product of a Bayesian analysis is the joint posterior probability distribution of all unknowns in the model. For point estimates, posterior means were used. Posterior standard deviations were reported as analogues to the standard error of an estimate from a classical (non-Bayesian) statistical analysis.

Mixture model results were more robust to length measurement error if only a minimal number of tethered fish data points were used, so a subset of tethered fish data from 2007 DIDSON experiments (Burwen 2010) provided a mildly informative prior for the β_0 and β_1 parameters. Species proportions π_C and π_S were assigned a Dirichlet(0.1,0.9) prior. This is a very mildly informative prior distribution, equivalent to a single additional observation and centered on 10% Chinook salmon rather than 50% for the noninformative beta(0.5,0.5). Prior distributions for age proportions $\{\theta_{Ca}\}$ and $\{\theta_{Sa}\}$ were constructed with nested beta(0.5,0.5) prior distributions. Netting probability of capture was assumed to be equal for all 3 age classes. Netting length data (Perschbacher 2015) from days $d-3$ through $d+3$ were paired with DIDSON length data from day d .

After 14 July, “Fast-Track” (FT) fish judged to be less than 75 cm, but not included in the measured subset of medium-sized fish, were modeled as having come from a censored sample. A test conducted on 2010 data found extremely good agreement between Chinook salmon proportions estimated with standard versus FT protocols. Between 4 July and 4 August 2010, 29 days with uncensored data were censored and reanalyzed with the FT protocol, yielding a 0.9994 to 1.0 relationship with a coefficient of determination of 0.998.

-continued-

⁷ During initial development of the model, multiple chains were used to assess convergence (Gelman et al. 2004). This was not necessary during subsequent annual updates.

A single Markov chain⁸ was initiated for each daily run of the DIDSON-length mixture model, samples were thinned 10 to 1, and history plots were monitored to confirm convergence and mixing. The first 5,000 or more “burn-in” samples were discarded, and at least 10,000 additional samples were drawn from the posterior distribution.

WinBUGS code for the DIDSON length mixture model is in Appendix B5. Model statements for censored observations under FT protocol are in the last paragraph of Appendix B6.

Posterior means are reported herein as point estimates and posterior standard deviations as standard errors.

See Fleischman and Burwen (2003) for an application of these methods to split-beam sonar data. Some of the methodological details used for this report differ from those used to produce preliminary 2010–2012 mixture model estimates that were reported elsewhere (Fleischman 2013: Table 4; and McKinley 2013: Table 5). These modifications are summarized in Appendix B7.

⁸ During initial development of the model, multiple chains were used to assess convergence (Gelman et al. 2004). This was not necessary during production of daily estimates.

Appendix B4.–WinBUGS code for a hierarchical age-composition model used to develop prior distributions for the DIDSON-length mixture model.

Age Mixture.odc version 6a:

```
model {
  #Overall means and std deviations
  for (a in 1:A) {
    sigma[a] ~ dnorm ( 0,1.0E-4) I ( 0,)
    tau[a] <- 1 / sigma[a] / sigma[a]
    mu[a] ~ dnorm ( 0,1.0E-12) I ( 0,)
  }
  #Dirichlet distributed age proportions across years within weeks
  D.scale ~ dunif ( 0,1)
  D.sum <- 1 / ( D.scale * D.scale)
  for (w in 1:W) {
    pi[w,1] ~ dbeta ( 0.2,0.4)
    pi.2p[w] ~ dbeta ( 0.2,0.2)
    pi[w,2] <- pi.2p[w] * ( 1 - pi[w,1])
    pi[w,3] <- 1 - pi[w,1] - pi[w,2]
    for (y in 1:Y) {
      for (a in 1:A) {
        D[w,y,a] <- D.sum * pi[w,a]
        g[w,y,a] ~ dgamma ( D[w,y,a],1)
        pi.wy[w,y,a] <- g[w,y,a]/sum ( g[w,y,])
      }
    }
  }
  for (i in 1:nfish) {
    age[i] ~ dcat ( pi.wy[week[i],year[i],1:A])
    length[i] ~ dnorm ( mu[age[i]],tau[age[i]])
  }
}
```

Note: Prior distributions in green font, likelihoods in blue.

```

model{
  beta0 ~ dnorm(75,0.0025)
  beta1 ~ dnorm(0.8,25)
  sigma.DL ~ dunif(0,20)
  tau.DL <- 1 / sigma.DL / sigma.DL
  ps[1:2] ~ ddirch(D.species[])
  pa[1,1] ~ dbeta(0.5,0.5)
  theta1 ~ dbeta(0.5,0.5)
  pa[1,2] <- theta1 * (1 - pa[1,1])
  pa[1,3] <- 1 - pa[1,1] - pa[1,2]
  pa[2,1] ~ dbeta(0.5,0.5)
  theta2 ~ dbeta(0.5,0.5)
  pa[2,2] <- theta2 * (1 - pa[2,1])
  pa[2,3] <- 1 - pa[2,1] - pa[2,2]
  n.chin <- ps[1] * ntgts
  p.large <- ps[1] * (1 - pa[1,1])
  n.large <- p.large * ntgts
  Lsig[1,1] <- 78
  Lsig[1,2] <- 70
  Lsig[1,3] <- 74
  Lsig[2,1] <- 25
  Lsig[2,2] <- 25
  Lsig[2,3] <- 25
  for (s in 1:2) {for (a in 1:3) {Ltau[s,a] <- 1 / Lsig[s,a] / Lsig[s,a] }}
  mu[1,1] ~ dnorm(621,0.0076)
  mu[1,2] ~ dnorm(825,0.0021)
  mu[1,3] ~ dnorm(1020,0.0047)
  mu[2,1] ~ dnorm(380,0.0004)
  mu[2,2] ~ dnorm(500,0.0004)
  mu[2,3] ~ dnorm(580,0.0004)
  for (a in 1:3) {
    pa.effective[1,a] <- pa[1,a] * q1.a[a] / inprod(pa[1,],q1.a[])
    pa.effective[2,a] <- pa[2,a]
  }
  for (k in 1:5) {
    TL.cm.75[k] <- TL.cm[k] - 75
    mu.DL1[k] <- beta0 + beta1 * TL.cm.75[k]
    DL1[k] ~ dnorm(mu.DL1[k],tau.DL)
  }
  for (i in 1:nfish) {
    age[i] ~ dcat(pa.effective[species[i],1:3])
    mefl.mm[i] ~ dnorm(mu[species[i],age[i]],Ltau[species[i],age[i]])
  }
  for (j in 1:ntgts) {
    species2[j] ~ dcat(ps[])
    age2[j] ~ dcat(pa[species2[j],1:3])
    mefl.mm.2[j] ~ dnorm(mu[species2[j],age2[j]],Ltau[species2[j],age2[j]])
    TL2.cm.75[j] <- (1.1*mefl.mm.2[j] + 2) / 10 - 75 # CONVERT TO TL -NUSHAGAK 2001 DATA
    mu.DL2[j] <- beta0 + beta1 * TL2.cm.75[j]
    DL2[j] ~ dnorm(mu.DL2[j],tau.DL)
  }
}

```

Note: Prior distributions in green font, likelihoods in blue.

```

for (j in 1:n_meas) {
  species2[j] ~ dcat(ps[])
  age2[j] ~ dcat(pa[species2[j],1:3])
  mefl.mm.2[j] ~ dnorm(mu[species2[j],age2[j]],Ltau[species2[j],age2[j]])
  TL2.cm.75[j] <- (1.1*mefl.mm.2[j]) / 10 - 75
  mu.DL2[j] <- beta0 + beta1 * TL2.cm.75[j]
  DL2[j] ~ dnorm(mu.DL2[j],tau.DL)I(40,)
}
for (k in 1:n_small) {
  species3[k] ~ dcat(ps[])
  age3[k] ~ dcat(pa[species3[k],1:3])
  mefl.mm.3[k] ~ dnorm(mu[species3[k],age3[k]],Ltau[species3[k],age3[k]])
  TL3.cm.75[k] <- (1.1*mefl.mm.3[k] + 2) / 10 - 75
  mu.DL3[k] <- beta0 + beta1 * TL3.cm.75[k]
  DL3[k] ~ dnorm(mu.DL3[k],tau.DL)I(75)
}
}

```

Note: Statements replace last paragraph of Appendix B5. Likelihoods are in blue. Data DL3 are unmeasured fish judged to be less than 75 cm.

Appendix B7.—Methodological details differing from previously published estimates.

Preliminary values of some of the estimates in this report were published by Fleischman (2013: Table 4, for late-run Chinook salmon) and McKinley (2013: Table 5, for early-run Chinook salmon). Technical methodological details that differed between preliminary and final estimates for 2010 and 2011 are summarized here.

Modification	Preliminary ^a		Final ^b
	2010	2011–2012	2010–2013
Age composition prior	informative ^c	informative ^c	non-informative ^d
Species composition prior	Dirichlet(0.5,0.5)	Dirichlet(0.5,0.5)	Dirichlet(0.1,0.9)
Days of netting data pooled and paired with day d of sonar data	$d-1$ to d	$d-6$ to d	$d-3$ to $d+3$
Chinook salmon size selectivity by age class	0.61, 0.57, 0.41	0.61, 0.57, 0.41	1, 1, 1

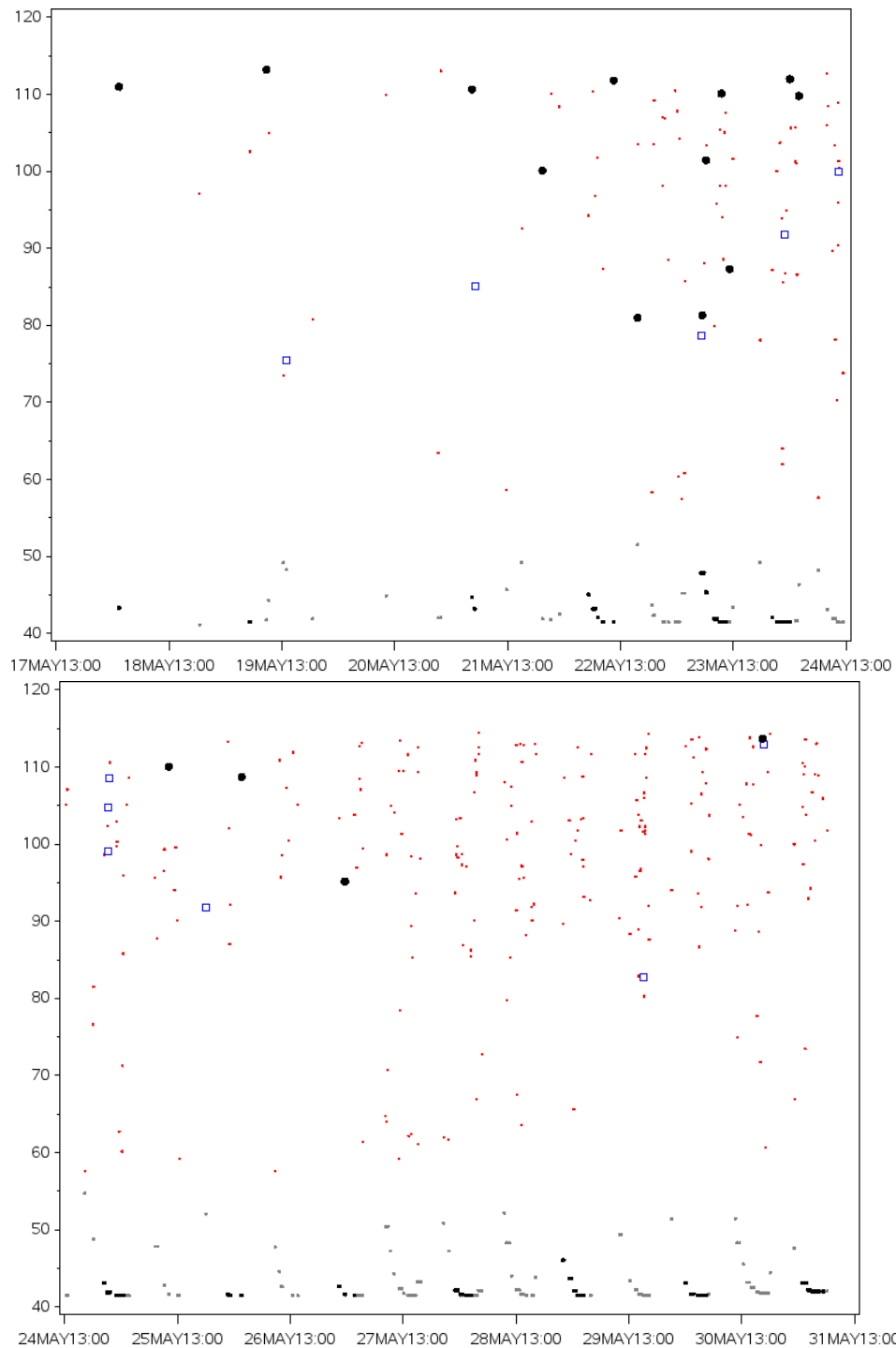
^a Used to produce results reported in McKinley (2013: Table 5) and Fleischman (2013: Table 4).

^b Used to produce results reported herein, in Miller (2013), Miller et al (2014), and in Miller (2015).

^c Informative priors differed by week, as developed from the hierarchical age composition model in Appendix B4.

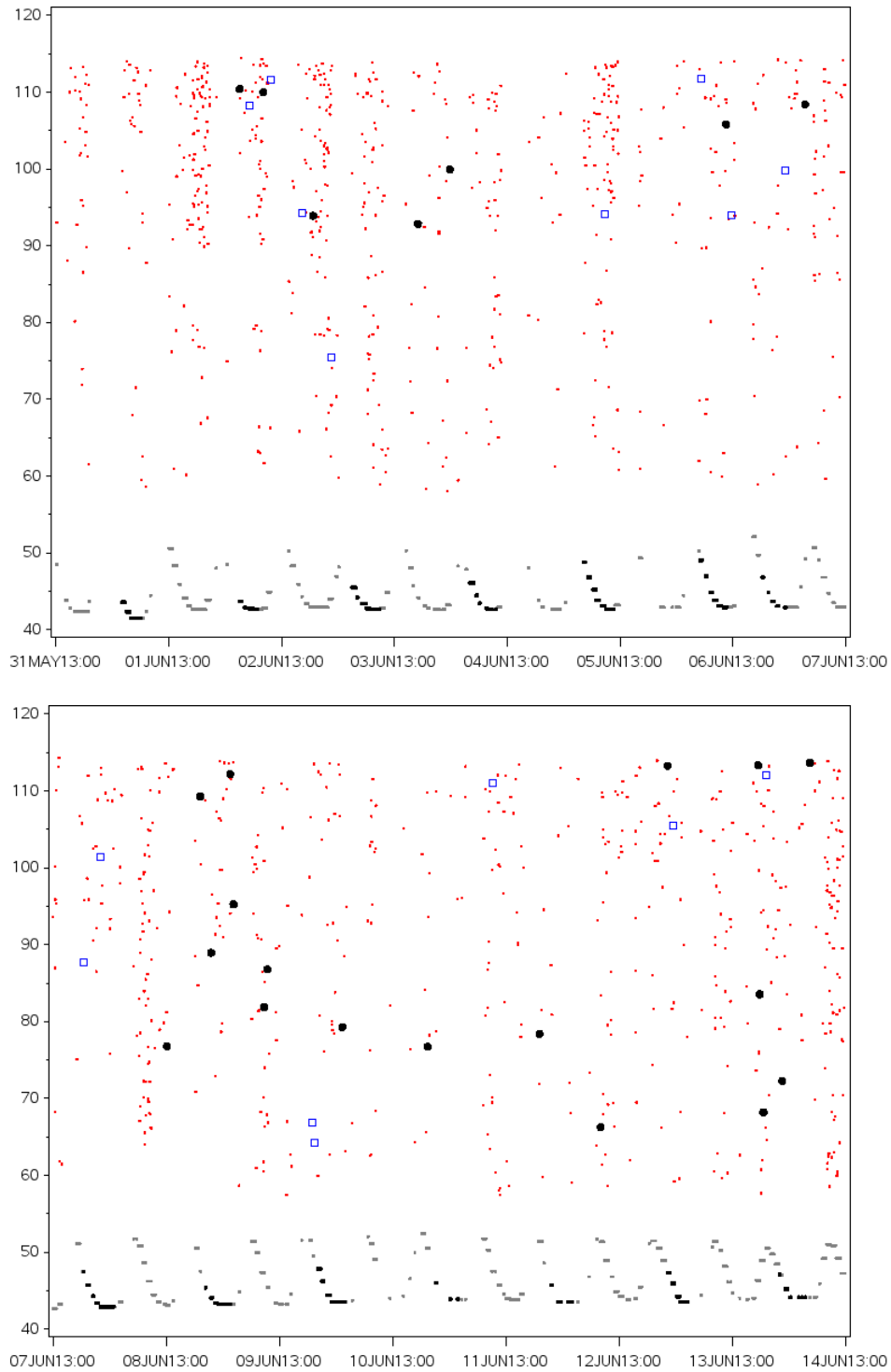
^d Noninformative nested beta priors (see Appendix B5).

**APPENDIX C: SPATIAL AND TEMPORAL DISTRIBUTION
OF FISH BY SIZE AS MEASURED BY DIDSON, RM 8.6
KENAI RIVER, 2013**



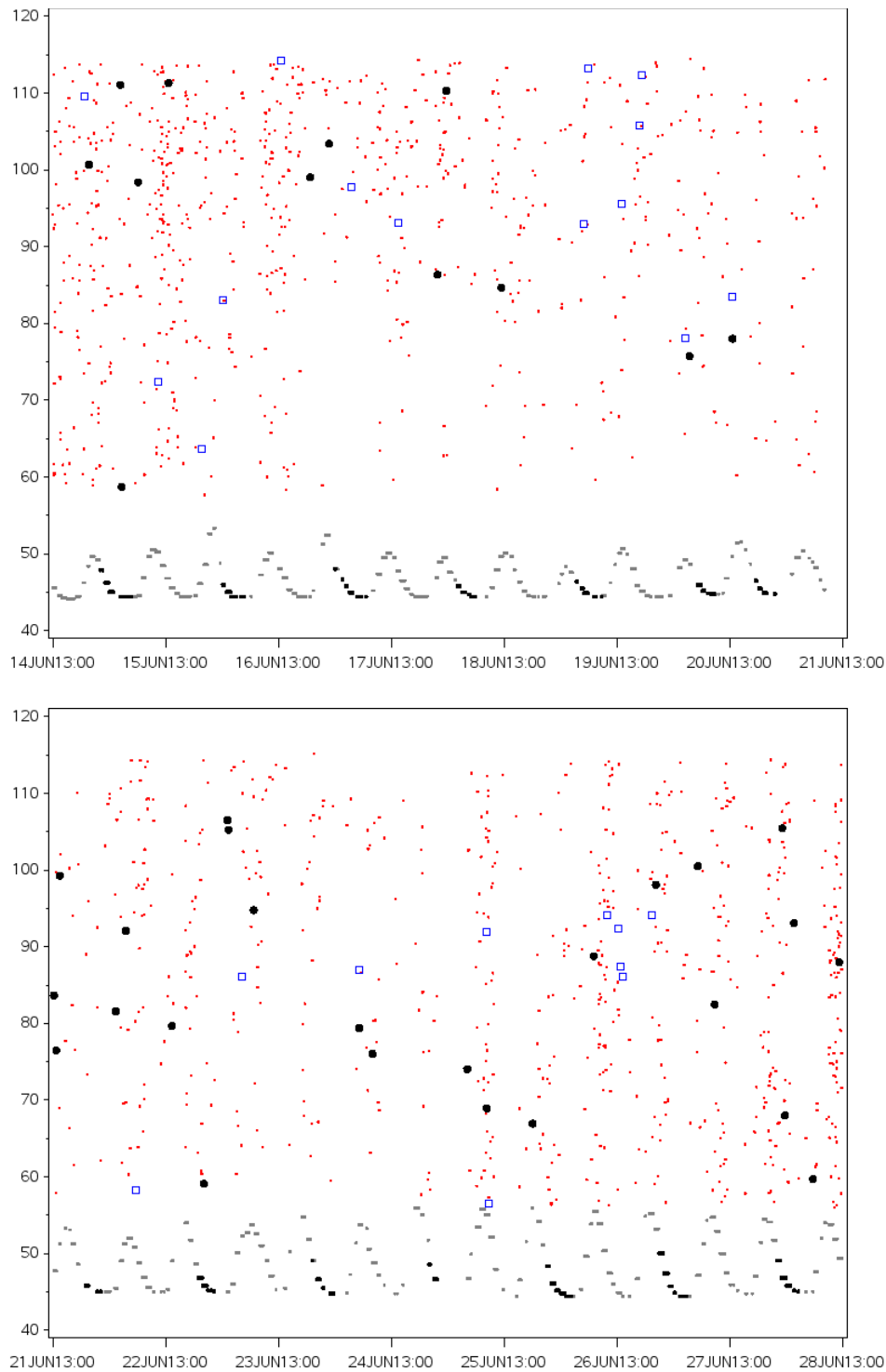
Appendix C1.—Spatial and temporal distribution of small (DIDSON length $DL < 75$ cm; small red symbols), medium ($75 \text{ cm} \leq DL < 90$ cm; larger blue squares), and large fish ($DL \geq 90$ cm; large black symbols), RM 8.6 Kenai River, 17–23 May (top) and 24–30 May (bottom) 2013.

Note: Vertical axis is distance (m) from benchmark on right-bank shore, except that relative water level is plotted at bottom (small grey symbols) with netting periods in black.



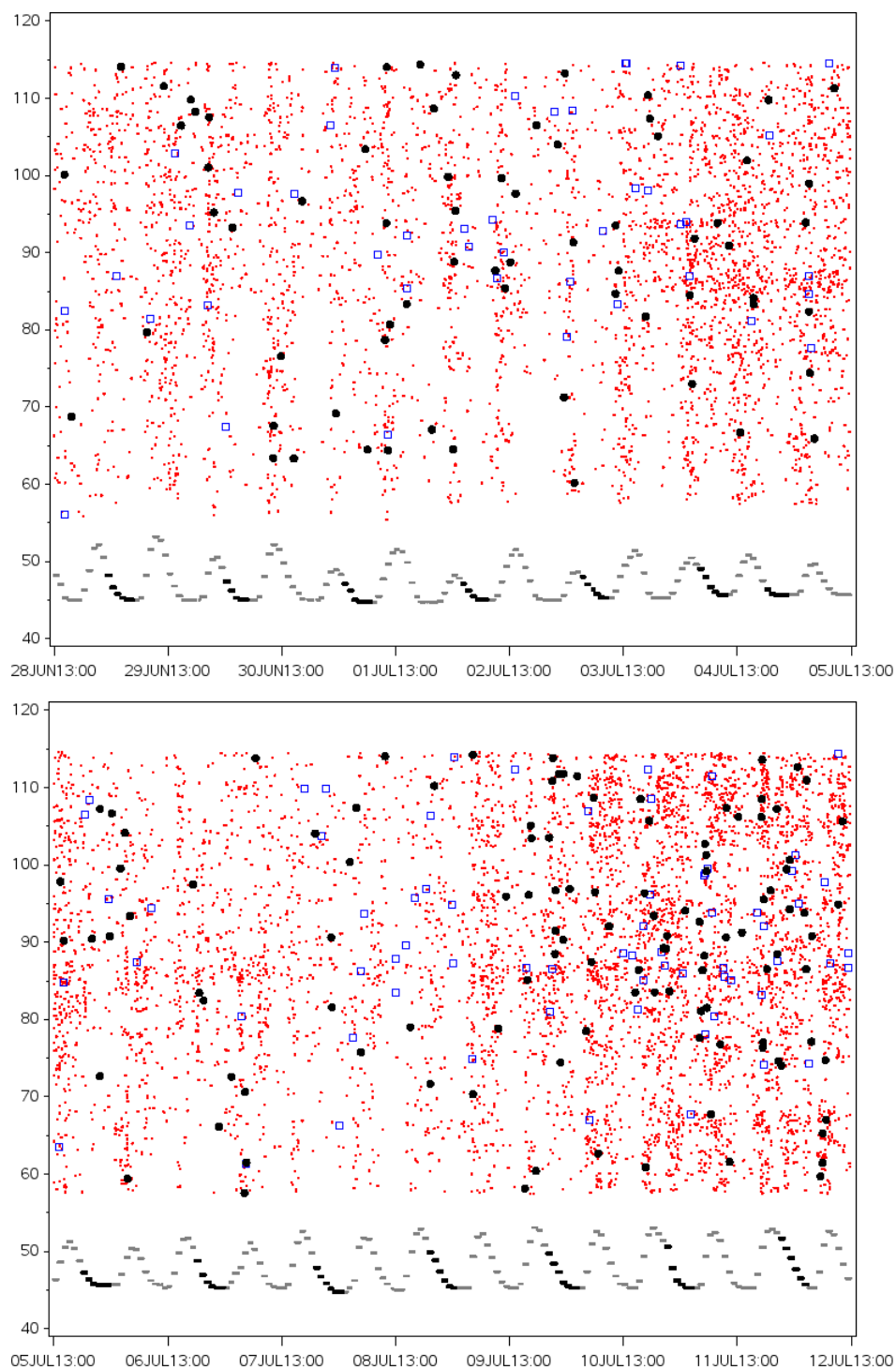
Appendix C2.—Spatial and temporal distribution of small (DIDSON length $DL < 75$ cm; small red symbols), medium ($75 \text{ cm} \leq DL < 90$ cm; larger blue squares), and large fish ($DL \geq 90$ cm; large black symbols), RM 8.6 Kenai River, 31 May–6 June (top) and 7–13 June (bottom) 2013.

Note: Vertical axis is distance (m) from benchmark on right-bank shore, except that relative water level is plotted at bottom (small grey symbols) with netting periods in black.



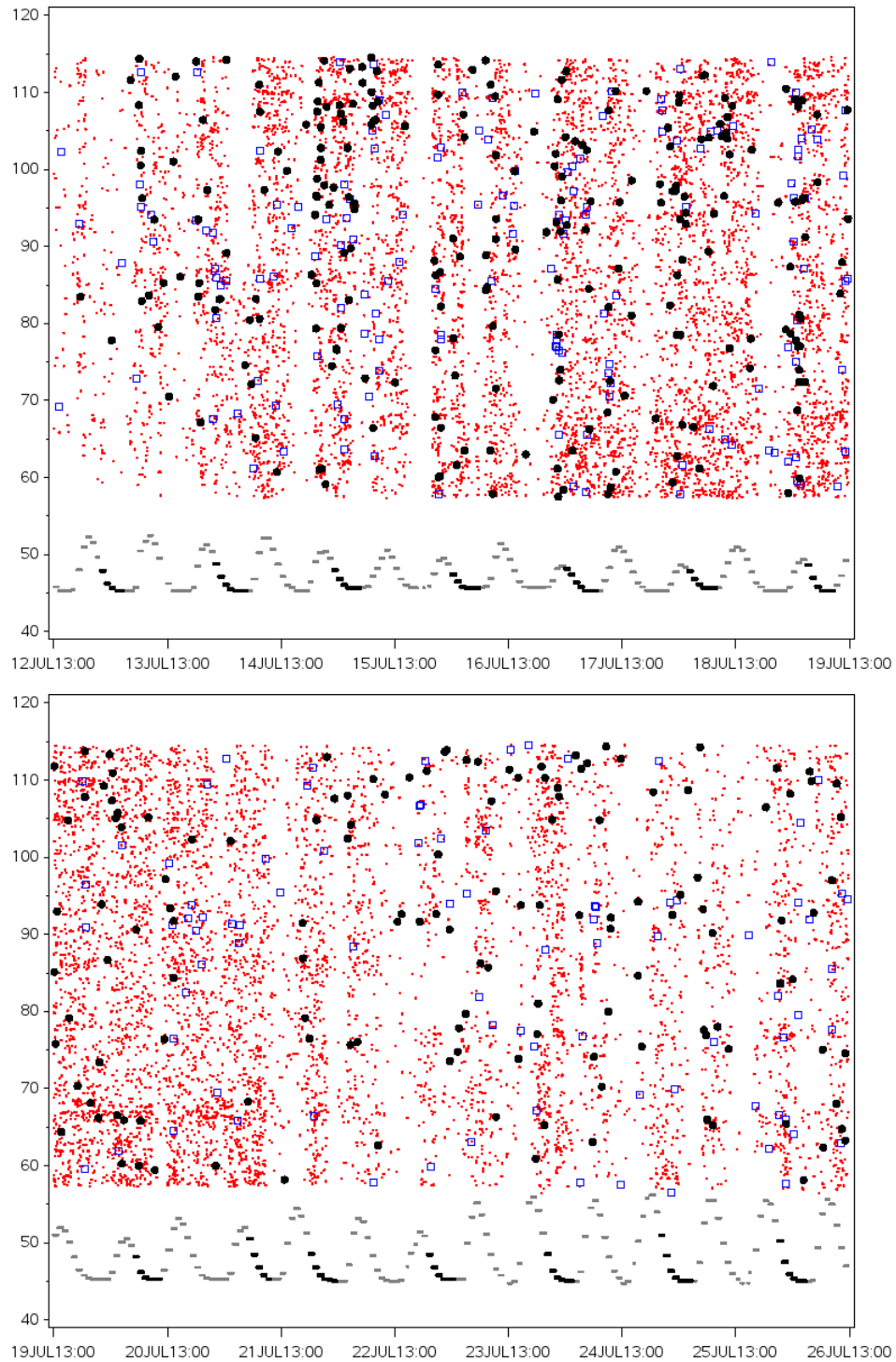
Appendix C3.—Spatial and temporal distribution of small (DIDSON length $DL < 75$ cm; small red symbols), medium ($75 \text{ cm} \leq DL < 90$ cm; larger blue squares), and large fish ($DL \geq 90$ cm; large black symbols), RM 8.6 Kenai River, 14–20 June (top) and 21–27 June (bottom) 2013.

Note: Vertical axis is distance (m) from benchmark on right-bank shore, except that relative water level is plotted at bottom (small grey symbols) with netting periods in black.



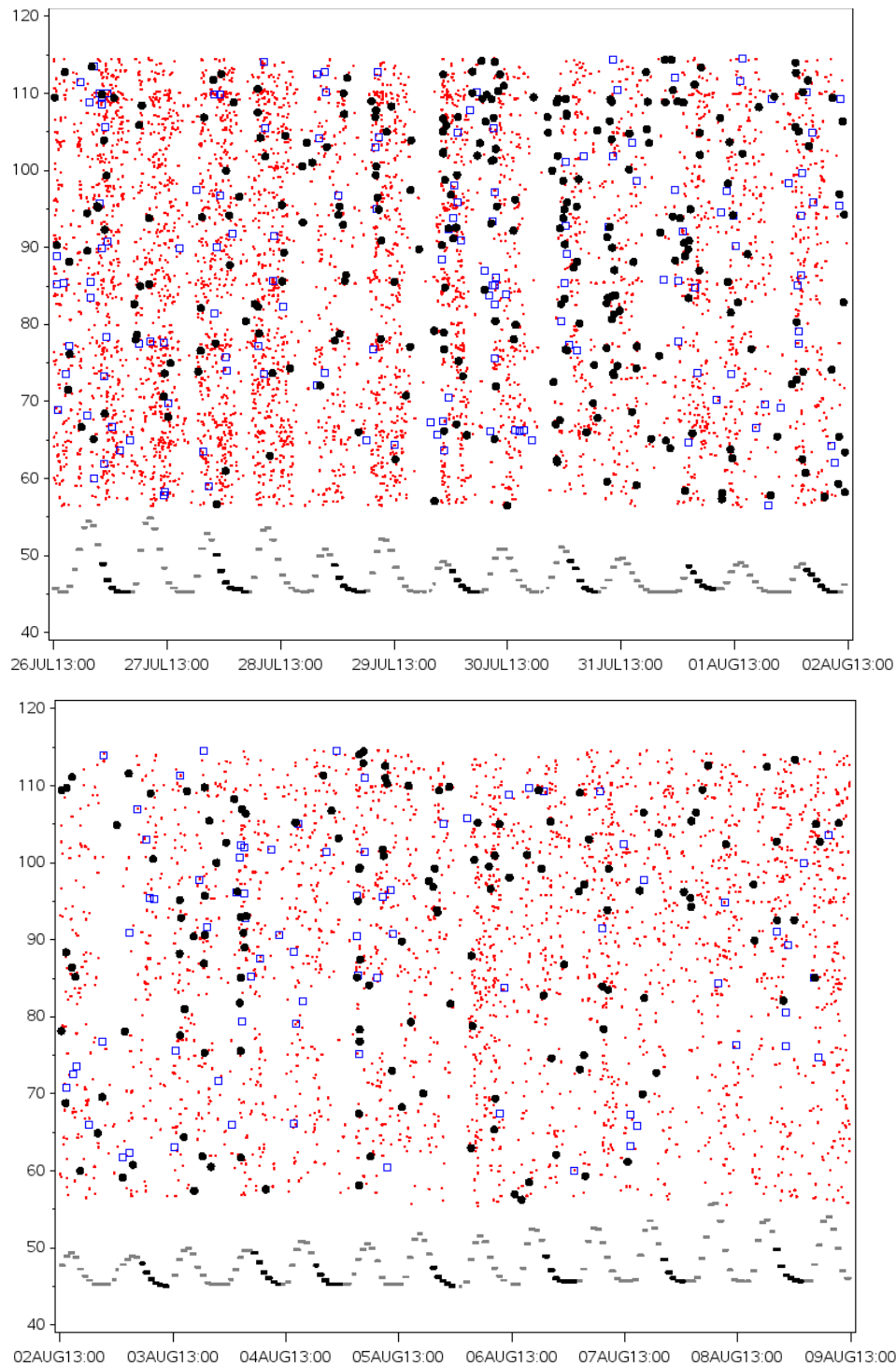
Appendix C4.—Spatial and temporal distribution of small (DIDSON length $DL < 75$ cm; small red symbols), medium ($75 \text{ cm} \leq DL < 90$ cm; larger blue squares), and large fish ($DL \geq 90$ cm; large black symbols), RM 8.6 Kenai River, 28 June–4 July (top) and 5–11 July (bottom) 2013.

Note: Vertical axis is distance (m) from benchmark on right-bank shore, except that relative water level is plotted at bottom (small grey symbols) with netting periods in black.



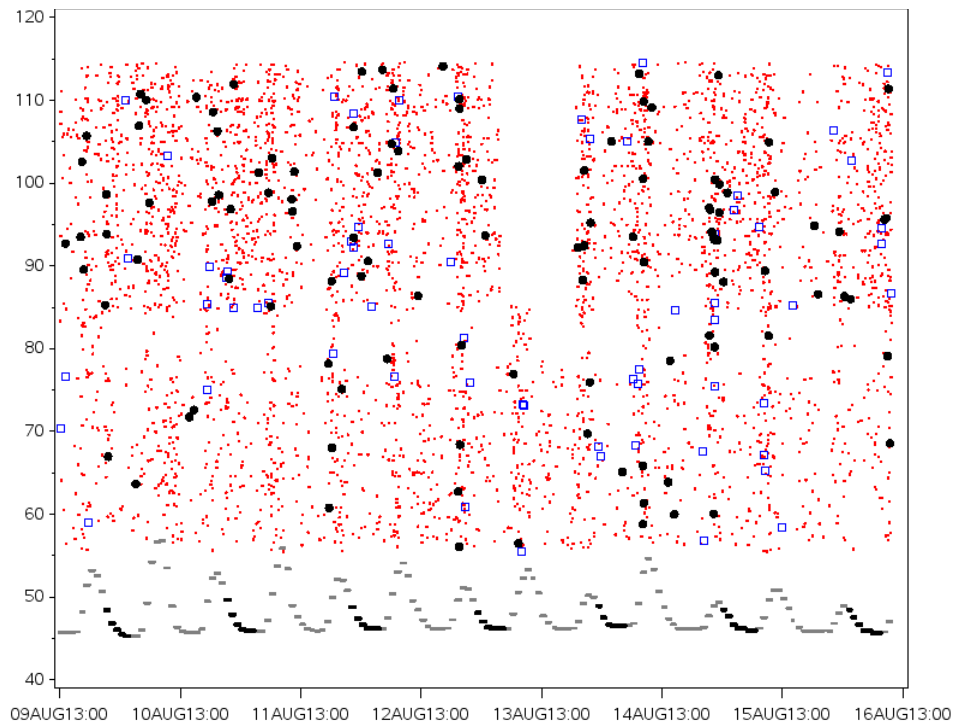
Appendix C5.—Spatial and temporal distribution of small (DIDSON length $DL < 75$ cm; small red symbols), medium ($75 \text{ cm} \leq DL < 90$ cm; larger blue squares), and large fish ($DL \geq 90$ cm; large black symbols), RM 8.6 Kenai River, 12–18 July (top) and 19–25 July (bottom) 2013.

Note: Vertical axis is distance (m) from benchmark on right-bank shore, except that relative water level is plotted at bottom (small grey symbols) with netting periods in black.



Appendix C6.—Spatial and temporal distribution of small (DIDSON length $DL < 75$ cm; small red symbols), medium ($75 \text{ cm} \leq DL < 90$ cm; larger blue squares), and large fish ($DL \geq 90$ cm; large black symbols), RM 8.6 Kenai River, 26 July –1 August (top) and 2–8 August (bottom) 2013.

Note: Vertical axis is distance (m) from benchmark on right-bank shore, except that relative water level is plotted at bottom (small grey symbols) with netting periods in black.



Appendix C7.—Spatial and temporal distribution of small (DIDSON length $DL < 75$ cm; small red symbols), medium ($75 \text{ cm} \leq DL < 90$ cm; larger blue squares), and large fish ($DL \geq 90$ cm; large black symbols), RM 8.6 Kenai River, 9–15 August 2013.

Note: Vertical axis is distance (m) from benchmark on right-bank shore, except that relative water level is plotted at bottom (small grey symbols) with netting periods in black.

**APPENDIX D: DIRECTION OF TRAVEL OF LARGE FISH
DETECTED BY DIDSON, RM 8.6 KENAI RIVER, 2013**

Appendix D1.–Daily numbers and proportions of upstream- and downstream-moving fish greater than or equal to 75 cm DIDSON length for the early run, RM 8.6 Kenai River, 2013.

Date	Total fish sampled	Number moving downstream	Number moving upstream	Percent moving downstream	Percent moving upstream
16 May	0	0	0		
17 May	1	0	1	0%	100%
18 May	1	0	1	0%	100%
19 May	1	0	1	0%	100%
20 May	2	0	2	0%	100%
21 May	2	0	2	0%	100%
22 May	6	0	6	0%	100%
23 May	6	2	4	33%	67%
24 May	4	0	4	0%	100%
25 May	2	0	2	0%	100%
26 May	1	0	1	0%	100%
27 May	2	2	0	100%	0%
28 May	0	0	0		
29 May	1	0	1	0%	100%
30 May	2	0	2	0%	100%
31 May	0	0	0		
1 Jun	4	0	4	0%	100%
2 Jun	3	0	3	0%	100%
3 Jun	2	0	2	0%	100%
4 Jun	1	0	1	0%	100%
5 Jun	3	0	3	0%	100%
6 Jun	2	0	2	0%	100%
7 Jun	2	0	2	0%	100%
8 Jun	7	0	7	0%	100%
9 Jun	3	0	3	0%	100%
10 Jun	2	0	2	0%	100%
11 Jun	2	0	2	0%	100%
12 Jun	2	0	2	0%	100%
13 Jun	6	0	6	0%	100%
14 Jun	6	0	6	0%	100%
15 Jun	3	0	3	0%	100%
16 Jun	4	0	4	0%	100%
17 Jun	4	0	4	0%	100%
18 Jun	2	0	2	0%	100%
19 Jun	5	0	5	0%	100%
20 Jun	2	0	2	0%	100%

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Date	Total fish sampled	Number moving downstream	Number moving upstream	Percent moving downstream	Percent moving upstream
21 Jun	7	1	6	14%	86%
22 Jun	8	2	6	25%	75%
23 Jun	3	0	3	0%	100%
24 Jun	4	0	4	0%	100%
25 Jun	4	1	3	25%	75%
26 Jun	7	0	7	0%	100%
27 Jun	5	0	5	0%	100%
28 Jun	9	0	9	0%	100%
29 Jun	16	1	15	6%	94%
30 Jun	16	1	15	6%	94%
Total	173	10	165	5.7%	94.3%

Appendix D2.–Daily numbers and proportions of upstream- and downstream-moving fish greater than or equal to 75 cm DIDSON length for the late run, RM 8.6 Kenai River, 2013.

Date	Total fish sampled	Number moving downstream	Number moving upstream	Percent moving downstream	Percent moving upstream
1 Jul	20	1	19	5%	95%
2 Jul	20	2	18	10%	90%
3 Jul	18	1	17	6%	94%
4 Jul	21	4	17	19%	81%
5 Jul	18	0	18	0%	100%
6 Jul	11	0	11	0%	100%
7 Jul	14	0	14	0%	100%
8 Jul	17	0	17	0%	100%
9 Jul	30	0	30	0%	100%
10 Jul	50	1	49	2%	98%
11 Jul	44	0	44	0%	100%
12 Jul	23	0	23	0%	100%
13 Jul	45	0	45	0%	100%
14 Jul	82	1	81	1%	99%
15 Jul	50	0	50	0%	100%
16 Jul	79	5	74	6%	94%
17 Jul	62	2	60	3%	97%
18 Jul	64	1	63	2%	98%
19 Jul	38	0	38	0%	100%
20 Jul	26	0	26	0%	100%
21 Jul	24	2	22	8%	92%
22 Jul	34	1	33	3%	97%
23 Jul	42	1	41	2%	98%
24 Jul	30	5	25	17%	83%
25 Jul	43	3	40	7%	93%
26 Jul	62	1	61	2%	98%
27 Jul	46	0	46	0%	100%
28 Jul	48	1	47	2%	98%
29 Jul	83	2	81	2%	98%
30 Jul	77	1	76	1%	99%
31 Jul	67	3	64	4%	96%

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Date	Total fish sampled	Number moving downstream	Number moving upstream	Percent moving downstream	Percent moving upstream
1 Aug	54	0	54	0%	100%
2 Aug	31	0	31	0%	100%
3 Aug	52	1	51	2%	98%
4 Aug	46	4	42	9%	91%
5 Aug	30	0	30	0%	100%
6 Aug	29	0	29	0%	100%
7 Aug	22	0	22	0%	100%
8 Aug	21	1	20	5%	95%
9 Aug	21	0	21	0%	100%
10 Aug	27	1	26	4%	96%
11 Aug	30	1	29	3%	97%
12 Aug	21	0	21	0%	100%
13 Aug	29	0	29	0%	100%
14 Aug	37	0	37	0%	100%
15 Aug	17	0	17	0%	100%
Total	1,755	46	1,709	2.6%	97.4%

**APPENDIX E: DIDSON LENGTH THRESHOLD
ESTIMATES OF LARGE CHINOOK SALMON, RM 8.6
KENAI RIVER, 2013**

Appendix E1.–Daily DIDSON length (DL) threshold estimates of large Chinook salmon passage (DL ≥ X cm) at RM 8.6 in the Kenai River, early run 2013.

Date	DL ≥ 75 cm		DL ≥ 80 cm		DL ≥ 90 cm	
	Passage	SE	Passage	SE	Passage	SE
16 May	0	0	0	0	0	0
17 May	6	5	6	5	6	5
18 May	6	5	6	5	6	5
19 May	6	5	0	0	0	0
20 May	12	5	12	5	6	5
21 May	12	7	12	7	12	7
22 May	36	12	30	9	30	9
23 May	24	10	24	10	12	7
24 May	29	17	22	13	18	15
25 May	12	7	12	7	6	5
26 May	6	5	6	5	6	5
27 May	0	0	0	0	0	0
28 May	0	0	0	0	0	0
29 May	6	5	0	0	0	0
30 May	12	10	6	5	6	5
31 May	0	0	0	0	0	0
1 Jun	24	9	24	9	12	7
2 Jun	18	9	12	7	6	5
3 Jun	12	7	12	7	12	7
4 Jun	6	5	0	0	0	0
5 Jun	18	6	18	6	6	5
6 Jun	12	7	6	5	6	5
7 Jun	12	7	6	5	0	0
8 Jun	42	11	42	11	42	11
9 Jun	18	7	12	7	6	5
10 Jun	12	7	12	7	6	5
11 Jun	12	7	12	7	12	7
12 Jun	12	5	12	5	6	5
13 Jun	36	11	36	11	30	11
14 Jun	36	13	36	13	24	12
15 Jun	18	8	6	4	6	4
16 Jun	24	9	24	9	12	7
17 Jun	24	9	24	9	18	8
18 Jun	12	5	6	5	0	0
19 Jun	34	10	30	9	6	5
20 Jun	12	7	12	7	6	4

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Date	DL \geq 75 cm		DL \geq 80 cm		DL \geq 90 cm	
	Passage	SE	Passage	SE	Passage	SE
21 Jun	36	10	30	9	30	9
22 Jun	36	14	36	14	30	13
23 Jun	18	11	18	11	12	7
24 Jun	24	16	12	7	12	7
25 Jun	18	9	18	9	12	7
26 Jun	42	10	36	10	18	9
27 Jun	30	13	30	13	30	13
28 Jun	54	16	54	16	30	9
29 Jun	90	19	84	16	60	15
30 Jun	90	28	78	26	60	21
Total	999	68	874	61	618	53

Note: All estimates are of upstream-bound fish in midriver between and greater than 3 m from the transducers.

Appendix E2.–Daily DIDSON length (DL) threshold estimates of large Chinook salmon passage (DL \geq X cm) at RM 8.6 in the Kenai River, late run 2013.

Date	DL \geq 75 cm		DL \geq 80 cm		DL \geq 90 cm	
	Passage	SE	Passage	SE	Passage	SE
1 Jul	164	48	138	46	107	36
2 Jul	109	21	96	19	66	17
3 Jul	103	22	72	21	54	15
4 Jul	103	31	84	26	66	16
5 Jul	109	18	90	18	66	13
6 Jul	66	21	60	17	54	18
7 Jul	84	14	78	14	42	13
8 Jul	103	22	78	16	42	14
9 Jul	181	30	175	30	145	25
10 Jul	295	41	271	37	163	28
11 Jul	265	51	229	48	181	38
12 Jul	139	47	133	42	78	32
13 Jul	314	43	322	43	208	34
14 Jul	489	65	453	62	314	46
15 Jul	302	62	272	58	211	42
16 Jul	447	76	398	74	253	41
17 Jul	362	41	326	35	272	30
18 Jul	380	50	350	45	193	37
19 Jul	229	37	229	37	193	25
20 Jul	157	28	145	23	42	13
21 Jul	139	27	121	28	104	27
22 Jul	199	32	193	29	127	23
23 Jul	252	40	209	32	167	27
24 Jul	162	28	156	27	114	22
25 Jul	241	27	199	20	121	17
26 Jul	368	56	332	56	175	29
27 Jul	278	39	266	36	163	30
28 Jul	284	50	260	47	199	33
29 Jul	477	83	465	81	314	63
30 Jul	459	76	416	69	362	61
31 Jul	386	36	368	33	290	30

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Date	DL \geq 75 cm		DL \geq 80 cm		DL \geq 90 cm	
	Passage	SE	Passage	SE	Passage	SE
1 Aug	326	39	290	31	193	29
2 Aug	195	23	183	23	118	18
3 Aug	308	47	272	41	193	41
4 Aug	254	65	248	66	145	48
5 Aug	181	22	182	22	147	26
6 Aug	175	28	169	29	139	25
7 Aug	133	23	127	23	91	19
8 Aug	126	30	125	29	73	20
9 Aug	127	32	121	30	91	29
10 Aug	157	28	157	28	109	22
11 Aug	175	34	145	25	103	19
12 Aug	180	49	114	36	100	33
13 Aug	180	34	155	36	119	30
14 Aug	223	44	205	39	139	26
15 Aug	112	19	99	17	66	12
Total	10,498	285	9,576	265	6,712	206

Note: All estimates are of upstream-bound fish in midriver between and greater than 3 m from the transducers.

**APPENDIX F: NET-APPORTIONED ESTIMATES, RM 8.6
KENAI RIVER, 2013**

Appendix F1.–DIDSON-based upstream fish passage (all species) at split-beam ranges (greater than 10 m from the left-bank transducer and greater than 15 m from the right-bank transducer), proportion of fish that were Chinook salmon in the inriver netting project, and daily net-apportioned estimates of Chinook salmon passage at RM 8.6 in the Kenai River, early run 2013.

Date	DIDSON upstream salmon at split-beam ranges		Proportion Chinook salmon in inriver gillnets		Net-apportioned Chinook salmon estimates		
	Passage	SE	Proportion	SE	Passage	SE	CV
16 May	0	0	zero fish caught				
17 May	0	0	zero fish caught				
18 May	18	9	zero fish caught				
19 May	18	6	zero fish caught				
20 May	6	5	0.468	0.407	3	3	0.90
21 May	36	9	0.000	0.000	0	0	
22 May	151	27	0.160	0.144	24	22	0.91
23 May	163	36	0.174	0.193	28	31	1.12
24 May	140	33	0.135	0.013	19	5	0.25
25 May	78	34	zero fish caught				
26 May	87	17	0.000	0.000	0	0	
27 May	155	27	0.000	0.000	0	0	
28 May	151	29	0.000	0.000	0	0	
29 May	187	34	0.000	0.000	0	0	
30 May	109	23	0.000	0.000	0	0	
31 May	187	38	0.048	0.053	9	10	1.11
1 Jun	537	63	0.093	0.038	50	21	0.42
2 Jun	555	65	0.000	0.000	0	0	
3 Jun	283	52	0.000	0.000	0	0	
4 Jun	380	46	0.019	0.020	7	8	1.08
5 Jun	153	35	0.000	0.000	0	0	
6 Jun	283	71	0.146	0.053	41	18	0.44
7 Jun	434	62	0.392	0.183	170	82	0.48
8 Jun	295	47	0.221	0.061	65	21	0.32
9 Jun	176	37	0.180	0.067	32	13	0.42
10 Jun	175	27	0.000	0.000	0	0	
11 Jun	199	33	0.122	0.090	24	18	0.75
12 Jun	332	58	0.200	0.071	66	26	0.39
13 Jun	537	52	0.107	0.112	57	60	1.05
14 Jun	834	70	0.070	0.041	58	34	0.59
15 Jun	748	72	0.056	0.044	42	33	0.79
16 Jun	382	55	0.199	0.204	76	78	1.02
17 Jun	457	52	0.424	0.194	194	91	0.47
18 Jun	274	31	0.133	0.117	36	32	0.89
19 Jun	385	57	0.142	0.069	55	27	0.50
20 Jun	175	33	0.266	0.241	47	42	0.90

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Date	DIDSON upstream salmon at split-beam ranges		Proportion Chinook salmon in inriver gillnets		Net-apportioned Chinook salmon estimates		
	Passage	SE	Proportion	SE	Passage	SE	CV
21 Jun	309	42	0.416	0.139	129	46	0.36
22 Jun	332	44	0.000	0.000	0	0	
23 Jun	235	35	0.352	0.306	83	72	0.87
24 Jun	342	68	0.000	0.000	0	0	
25 Jun	508	79	0.336	0.165	171	87	0.51
26 Jun	456	61	0.209	0.097	95	46	0.48
27 Jun	723	68	0.205	0.201	148	145	0.98
28 Jun	1,953	147	0.078	0.034	152	67	0.44
29 Jun	2,502	231	0.118	0.056	295	142	0.48
30 Jun	1,775	151	0.000	0.000	0	0	
Total	18,215	433			2,176	312	0.14

Note: All estimates are germane to upstream-bound fish in midriver (greater than 10 m from the left-bank transducer and greater than 15 m from the right-bank transducer) for purposes of comparability with historical net-apportioned estimates based on split-beam sonar. See Net-apportioned Index sections in Methods and Results.

Appendix F2.—DIDSON-based upstream fish passage (all species) at split-beam ranges (greater than 10 m from the left-bank transducer and greater than 15 m from the right-bank transducer), proportion of fish that were Chinook salmon in the inriver netting project, and daily net-apportioned estimates of Chinook salmon passage at RM 8.6 in the Kenai River, late run 2013.

Date	DIDSON upstream salmon at split-beam ranges		Proportion Chinook salmon in inriver gillnets		Net-apportioned Chinook salmon estimates		
	Passage	SE	Proportion	SE	Passage	SE	CV
1 Jul	1,898	225	0.036	0.034	68	65	0.95
2 Jul	1,272	130	0.180	0.135	229	172	0.75
3 Jul	4,149	288	0.141	0.058	585	243	0.42
4 Jul	5,572	358	0.021	0.021	117	117	1.00
5 Jul	3,564	295	0.057	0.037	203	132	0.65
6 Jul	2,508	257	0.281	0.143	705	364	0.52
7 Jul	1,700	124	0.340	0.075	578	134	0.23
8 Jul	2,569	232	0.161	0.067	414	175	0.42
9 Jul	6,778	754	0.218	0.086	1,478	602	0.41
10 Jul	11,988	826	0.077	0.019	923	236	0.26
11 Jul	8,358	820	0.048	0.031	401	261	0.65
12 Jul	2,135	251	0.290	0.197	619	424	0.68
13 Jul	6,880	684	0.164	0.073	1,128	512	0.45
14 Jul	6,682	693	0.261	0.092	1,744	638	0.37
15 Jul	10,546	2,351	0.030	0.017	316	188	0.60
16 Jul	9,883	1,204	0.052	0.042	514	417	0.81
17 Jul	7,847	1,310	0.064	0.032	502	261	0.52
18 Jul	10,102	1,093	0.034	0.008	343	89	0.26
19 Jul	10,882	666	0.044	0.019	479	208	0.44
20 Jul	7,309	371	0.018	0.010	132	73	0.56
21 Jul	3,546	327	0.026	0.016	92	57	0.62
22 Jul	2,210	264	0.038	0.017	84	39	0.46
23 Jul	3,310	292	0.044	0.023	146	77	0.53
24 Jul	2,005	220	0.119	0.043	239	90	0.37
25 Jul	2,378	189	0.073	0.054	174	129	0.74
26 Jul	5,602	481	0.070	0.036	392	204	0.52
27 Jul	6,798	914	0.036	0.021	245	145	0.59
28 Jul	3,055	371	0.205	0.034	626	128	0.20
29 Jul	3,501	447	0.163	0.066	571	240	0.42
30 Jul	2,028	198	0.252	0.100	511	208	0.41
31 Jul	2,209	235	0.143	0.052	316	119	0.38

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Date	DIDSON upstream salmon at split-beam ranges		Proportion Chinook salmon in inriver gillnets		Net-apportioned Chinook salmon estimates		
	Passage	SE	Proportion	SE	Passage	SE	CV
1 Aug	2,083	216	0.153	0.068	319	145	0.45
2 Aug	1,096	76	0.087	0.044	95	49	0.51
3 Aug	1,775	179	0.053	0.042	94	75	0.80
4 Aug	1,885	228	0.102	0.039	192	77	0.40
5 Aug	2,338	250	0.032	0.039	75	91	1.21
6 Aug	2,041	174	0.135	0.087	276	178	0.65
7 Aug	1,739	79	0.099	0.035	172	61	0.36
8 Aug	2,050	146	0.062	0.035	127	72	0.57
9 Aug	3,180	234	0.184	0.053	585	174	0.30
10 Aug	3,208	376	0.013	0.011	42	35	0.84
11 Aug	2,869	304	0.062	0.048	178	138	0.78
12 Aug	3,684	507	0.067	0.053	247	196	0.79
13 Aug	3,503	402	0.000	0.000	0	0	
14 Aug	3,068	262	0.142	0.069	436	214	0.49
15 Aug	2,517	280	0.014	0.018	35	45	1.29
1 July–15 Aug	196,300	4,106			17,747	1,557	0.09

Note: all estimates are germane to upstream-bound fish in midriver (greater than 10 m from left-bank transducer and greater than 15 m from right-bank transducer) for purposes of comparability with historical net-apportioned estimates based on split-beam sonar. See Net-apportioned Index sections in Methods and Results.